CSC 580 Principles of Machine Learning

04 Practical Considerations

Jason Pacheco

Department of Computer Science



*slides credit: built upon CSC 580 lecture slides by Chicheng Zhang & Kwang-Sung Jun

The role of features in supervised learning

3

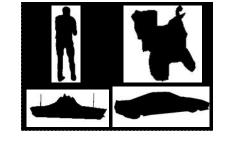
The importance of good feature representation

- Pixel representation:
 - represent an image as a w*h*3 dimensional vector
 - treat all coordinates in the same role
 - throw away all locality information in the image

- Shape representation:
 - represent a colored image with a w*h black-white image

• Bag-of-words representation:

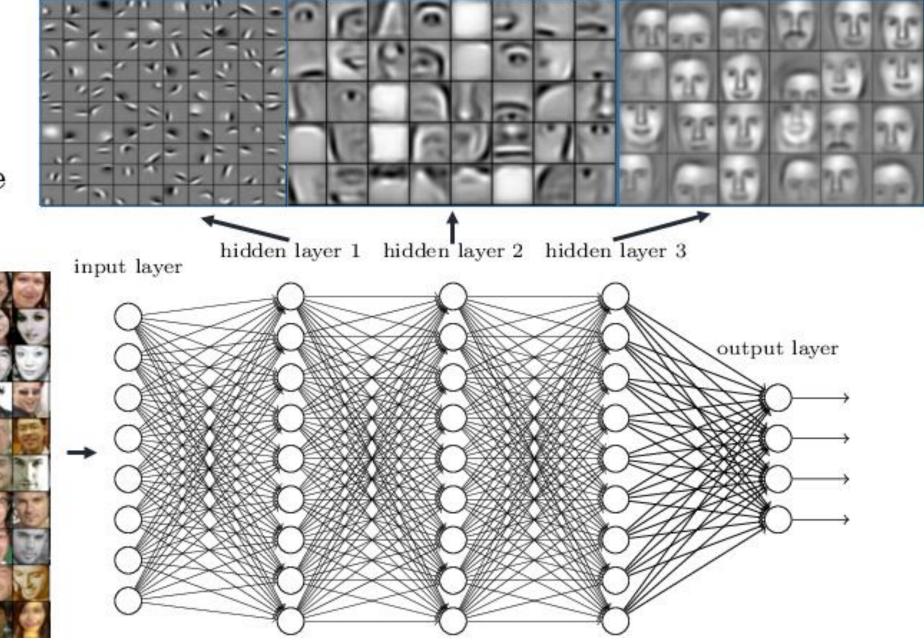
	free	offer	lecture	CS	Spam?
Email 1	2	1	0	0	+1
Email 2	0	1	3	1	-1

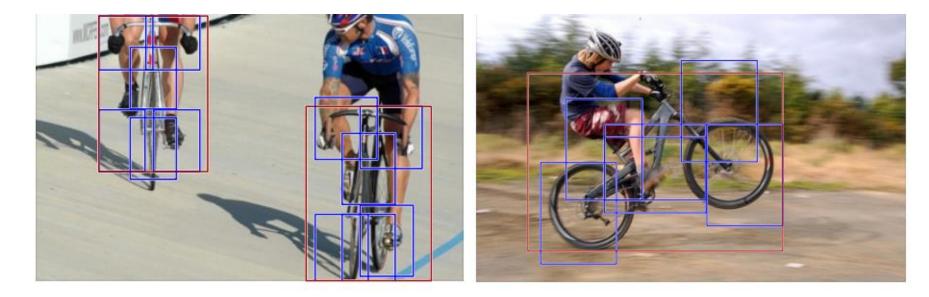


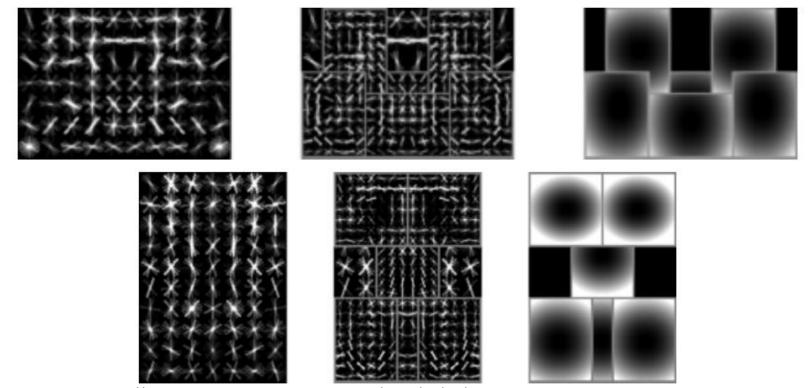




Deep neural networks learn hierarchical feature representations







https://computervisionblog.wordpress.com/2016/01/23/distributed-code-or-grandmother-cells-insights-from-convolutional-neural-networks/

Irrelevant and redundant features

- Irrelevant features
 - y is independent of f
 - y = Road walkability, f = duck activities in the pond

- If #features is large and #examples is small ⇒ spurious correlation between some feature & label
- Redundant features
 - Given f_1 , y is (nearly) independent of f_2
- Learning decision trees implicitly handles these two issues
- How about nearest neighbors / Perceptron?

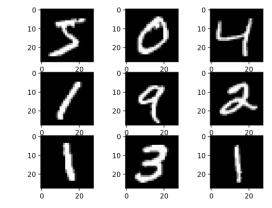


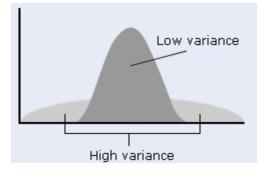


Feature pruning

- Removing features that are not very useful for prediction
 - E.g. text classification with bag-of-word representation, remove words that appear <= K docs
 - E.g. digit classification, remove pixels with low variance

$$\mu_f = \frac{1}{N} \sum_{i=1}^N x_{i,f} \quad \sigma_f^2 = \frac{1}{N} \sum_{i=1}^N (x_{i,f} - \mu_f)^2$$





Example: Prostate Cancer Dataset

Term	LS	Ridge	Lasso
Intercept	2.465	2.452	2.468
lcavol	0.680	0.420	0.533
lweight	0.263	0.238	0.169
age	-0.141	-0.046	
lbph	0.210	0.162	0.002
svi	0.305	0.227	0.094
lcp	-0.288	0.000	
gleason	-0.021	0.040	
pgg45	0.267	0.133	

Best LASSO model learns to ignore several features (age, lcp, gleason, pgg45).

Wait...Is **age** really not a significant predictor of prostate cancer? What's going on here?

Age is highly correlated with other factors and thus *not significant* in the presence of those factors

Best-Subset Feature Selection

The optimal strategy for p features looks at models over *all possible combinations* of features,

For k in 1,..., p:

subset = Compute all subset of k-features (p-choose-k)

```
For kfeat in subset:
```

model = Train model on kfeat features

score = Evaluate model using cross-validation

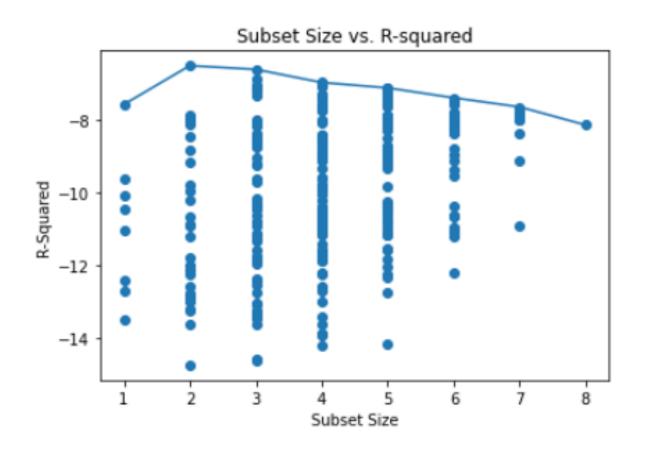
Choose the model with best cross-validation score

Best-Subset Feature Selection : Prostate Cancer Dataset

Each marker is the cross-val R² score of a trained model for a subset of features

Data have 8 features, there are 8-choose-k subsets for each k=1,...,8 for a total of 255 models

Using 10-fold cross-val requires 10 x 255 = 2,550 training runs!



Feature Selection: Prostate Cancer Dataset Best subset has highest test accuracy (lowest variance) with just 2 features

Term	LS	Best Subset	Ridge	Lasso
Intercept	2.465	2.477	2.452	2.468
lcavol	0.680	0.740	0.420	0.533
lweight	0.263	0.316	0.238	0.169
age	-0.141		-0.046	
lbph	0.210		0.162	0.002
svi	0.305		0.227	0.094
lcp	-0.288		0.000	
gleason	-0.021		0.040	
pgg45	0.267		0.133	
Test Error	0.521	0.492	0.492	0.479
Std Error	0.179	0.143	0.165	0.164

[Source: Hastie et al. (2001)]

Forward Sequential Selection

An efficient method adds the most predictive feature one-by-one

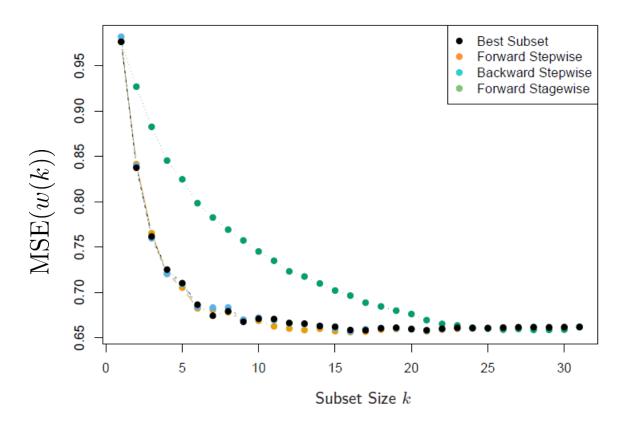
```
featSel = empty
featUnsel = All features
For iter in 1,..., p:
 For kfeat in featUnsel:
   thisFeat = featSel + kfeat
   model = Train model on thisFeat features
   score = Evaluate model using cross-validation
 featSel = featSel + best scoring feature
 featUnsel = featUnsel - best scoring feature
Choose the model with best cross-validation score
```

Backward Sequential Selection

Backwards approach starts with *all* features and removes one-by-one

```
featSel = All features
For iter in 1,..., p:
 For kfeat in featSel:
   thisFeat = featSel - kfeat
   model = Train model on thisFeat features
   score = Evaluate model using cross-validation
 featSel = featSel - worst scoring feature
Choose the model with best cross-validation score
```

Comparing Feature Selection Methods Sequential selection is greedy, but often performs well...



Example Feature selection on synthetic model with p=30 features with pairwise correlations (0.85). True feature weights are all zero except for 10 features, with weights drawn from N(0,6.25).

Sequential selection with p features takes $O(p^2)$ time, compared to exponential time for best subset

Sequential feature selection available in Scikit-Learn under: feature_selection.SequentialFeatureSelector

Feature normalization

• Centering:

•
$$x'_{i,f} = x_{i,f} - \mu_f \Rightarrow \mu'_f = 0$$

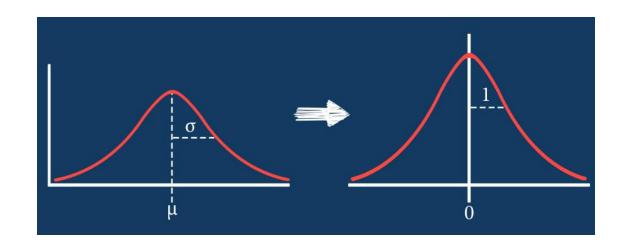
• Variance scaling:

•
$$x'_{i,f} = x_{i,f} / \sigma_f \Rightarrow (\sigma'_f)^2 = 1$$

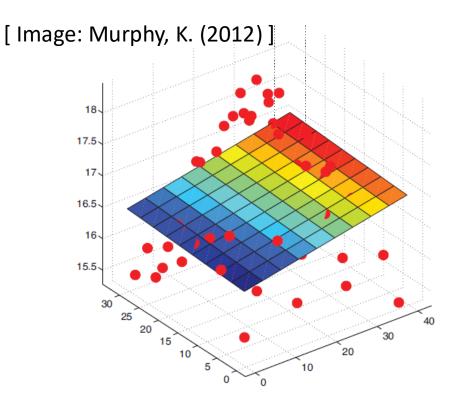
• Absolute scaling

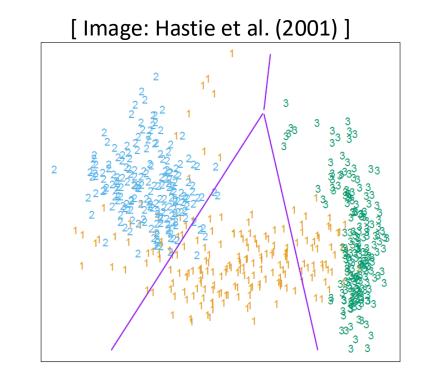
•
$$x'_{i,f} = x_{i,f}/r_f$$
, where $r_f = \max_i |x_{i,f}| \Rightarrow$ range of $x'_{i,f}$'s in [-1,+1]

- Same transformation applied to both training set and test data
- Aside: example normalization: $x'_i = \frac{x_i}{\|x_i\|}$ sometimes also can be applied



Linear Models





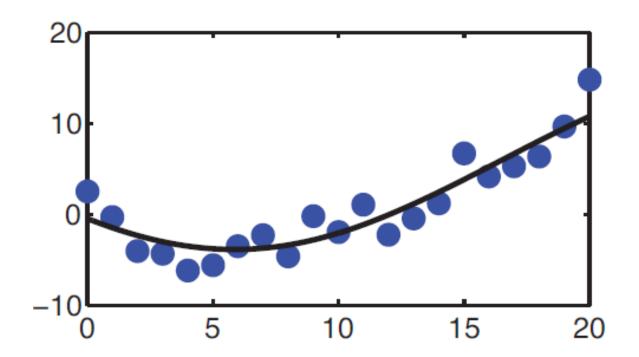
Linear Regression Fit a *linear function* to features,

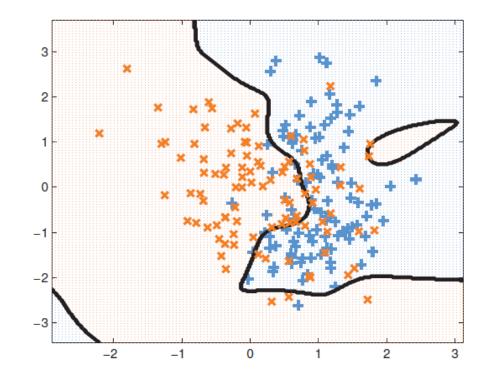
$$y = w^T x + b$$

Logistic Regression Learn a decision boundary that is *linear in the data*,

$$\operatorname{logit}(\sigma(w^T x)) = w^T x$$

Nonlinear Data





What if our data are *not* well-described by a linear function?

What if classes are *not linearly-separable*?

[Source: Murphy, K. (2012)]

Basis Functions

- A **basis function** can be any function of the input features X
- Define a set of m basis functions $\phi_1(x),\ldots,\phi_m(x)$
- Fit a linear regression model in terms of basis functions,

$$y = \sum_{i=1}^{m} w_i \phi_i(x) = w^T \phi(x)$$

- Regression model is *linear in the basis transformations*
- Model is *nonlinear in the data X*

Common "All-Purpose" Basis Functions

• Linear basis functions recover the original linear model,

 $\phi_m(x) = x_m$ Returns mth dimension of X

- Quadratic. $\phi_m(x) = x_j^2$ or $\phi_m(x) = x_j x_k$ capture 2nd order interactions
- An order p polynomial $\phi \to x_d, x_d^2, \dots, x_d^p$ captures higher-order nonlinearities (but requires $O(d^p)$ parameters)
- Nonlinear transformation of single inputs,

 $\phi \to (\log(x_j), \sqrt{x_j}, \ldots)$

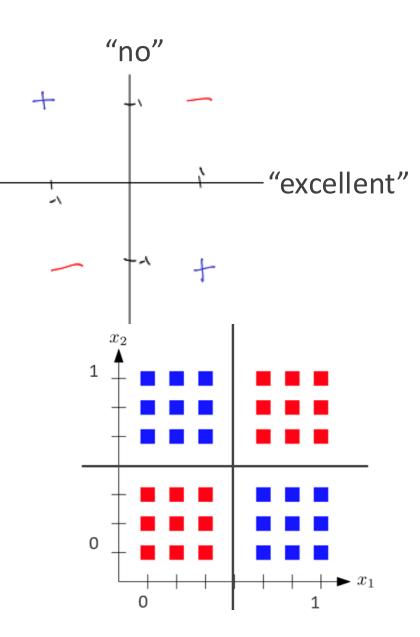
• An indicator function specifies a region of the input,

$$\phi_m(x) = I(L_m \le x_k < U_m)$$

Feature transformations

- Combining features into a "meta-feature", e.g. $x_{no} \cdot x_{excellent}$
 - Useful for e.g. Perceptron learners
- In general, $\binom{d}{k}$ meta-features if allowed to combine k features
- Computationally cheaper alternative:
 - train a decision tree, use the meta-feature induced by leaves

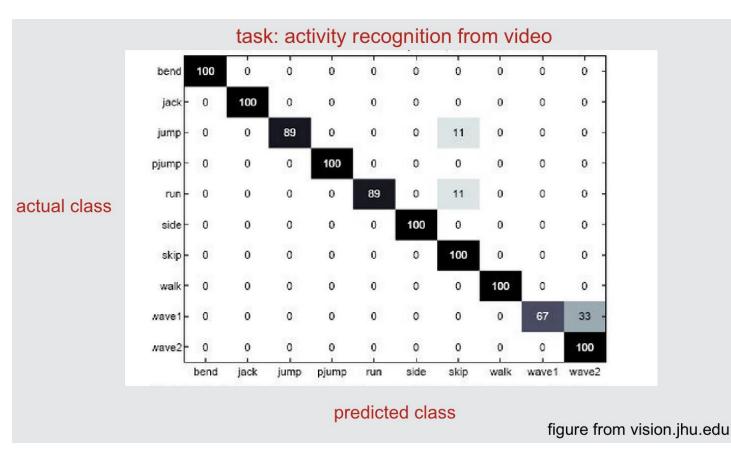
- Logarithmic feature transformation
 - $x'_f \leftarrow \log_2(x_f)$ ("excellent" word count: 1->2 vs. 10->11
 - $x'_f \leftarrow \log_2(x_f + 1)$



Classification metrics beyond error rate

Confusion matrix

- E.g. activity recognition
- $P(\hat{y} = \text{skip} | y = \text{jump}) = 11\%$



Class imbalance problem

- E.g., 5% pos, 95% negative.
- Solution 1: Duplication
 - Duplicate the minority in the train set so we have 50% pos, 50% neg.

Q: |S| = 100 with 95 +, 5 -. How much do we need to duplicate the neg example?

- Solution 2: <u>Weighting</u>
 - Change the algorithm so it takes weights $\{w_1, \dots, w_n\}$ for train set
 - E.g., *k*-NN

$$\arg \max_{c \in \{1,...,C\}} \sum_{i \in N(x)} w_i \cdot I\{y_i = c\} \quad \text{where } w_i = x \text{ if } y_i = 1 \\ = 1 \text{ otherwise}$$

• Solution 2 is preferred (many scikit-learn classifiers allow this), but some classifiers do not.

Solve 5x = 95

New measures of classification performance

• True positive rate (TPR)

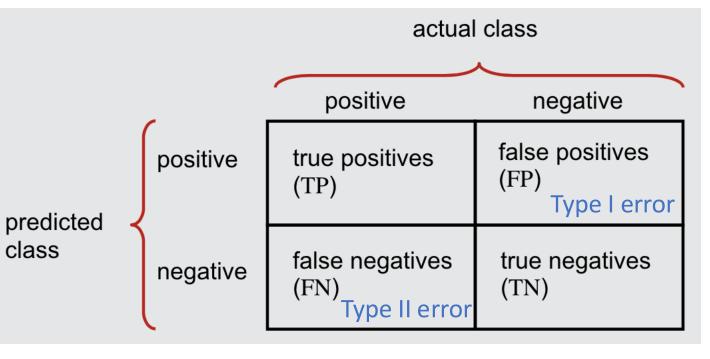
 $=\frac{\text{TP}}{\text{P}} = \frac{P(\hat{y}=+1,y=+1)}{P(y=+1)}$

(aka recall, sensitivity)

- True negative rate (TNR) = $\frac{TN}{N}$ (specificity)
- False positive rate (FPR) = $\frac{FP}{N}$

• False negative rate (FNR) =
$$\frac{FN}{P}$$

• Precision =
$$\frac{\text{TP}}{\text{P}-called} = \frac{P(\hat{y}=+1,y=+1)}{P(\hat{y}=+1)}$$
, P - called = TP + FP



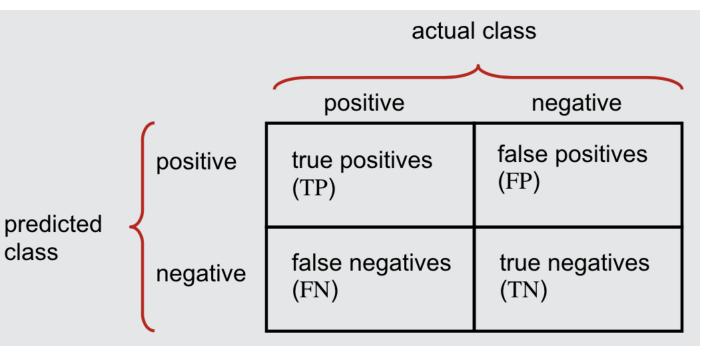
P = TP + FN N = FP + TN

Applications:

- Search engine: precision & recall
- Cancer classification: FNR vs. FPR

Adjust TP, FP, TN, FN

- Decision values
 - E.g., the predicted P(Y = 1 | X = x)
 - Some classifiers just have a real-value where positive value indicates positive prediction.
 (e.g, supper vector machine – will be covered later)



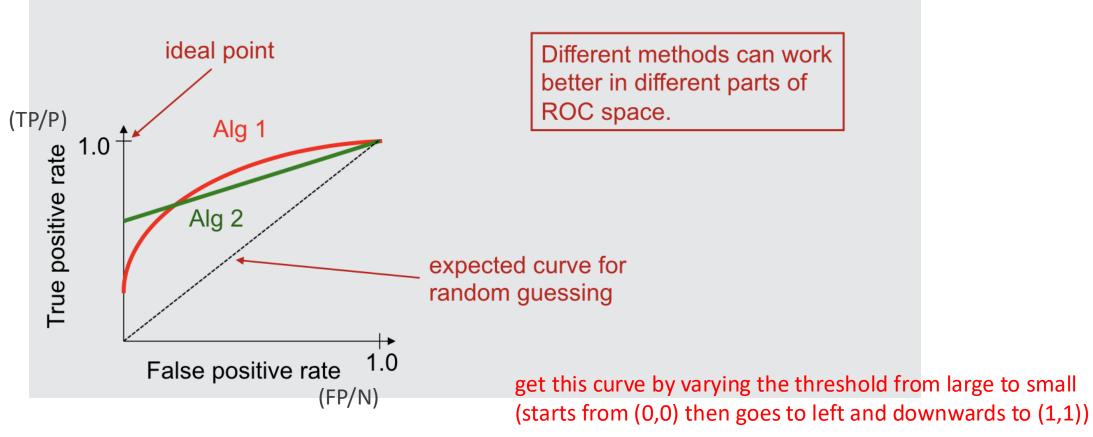
P = TP + FN N = FP + TN

- Default: $P(Y = 1 | X = x) \ge .5$ then call it positive
 - Threshold to $1.1 \Rightarrow$ always predict neg.
 - Threshold to $0 \Rightarrow$ always predict pos.



ROC curve

A *Receiver Operating Characteristic* (*ROC*) curve plots the TP-rate vs. the FP-rate as a threshold on the confidence of an instance being positive is varied



ROC curve

- <u>Conceptually</u>, consider every possible threshold, put a dot for each, and connect them.
- In practice, just need to care about when the 'correct class' changes from + to – or from – to +.
 - results in staircase shape, but diagonal line can still happen.
- confidence TPR=0, FPR=0 correct instance positive class Ex 9 .99 1.0 1 Ex 7 .98 TPR= 2/5, FPR= 0/5 + True positive rate Ex 1 .72 Ex 2 .70 .65 Ex 6 TPR= 4/5, FPR= 1/5 + Ex 10 .51 .39 Ex 3 Ex 5 .24 TPR= 5/5, FPR= 3/5 + 1.0 Ex 4 .11 False positive rate Ex 8 .01 TPR= 5/5, FPR= 5/5

 A popular alternative: just plot when going from + to -. (what's shown here)

decision value; sorted in decreasing order

ROC curve algorithm

let $\begin{pmatrix} (y^{(1)}, c^{(1)}) \dots (y^{(m)}, c^{(m)}) \end{pmatrix}$ be the test-set instances sorted according to predicted confidence $c^{(i)}$ that each instance is positive

let *num_neg*, *num_pos* be the number of negative/positive instances in the test set

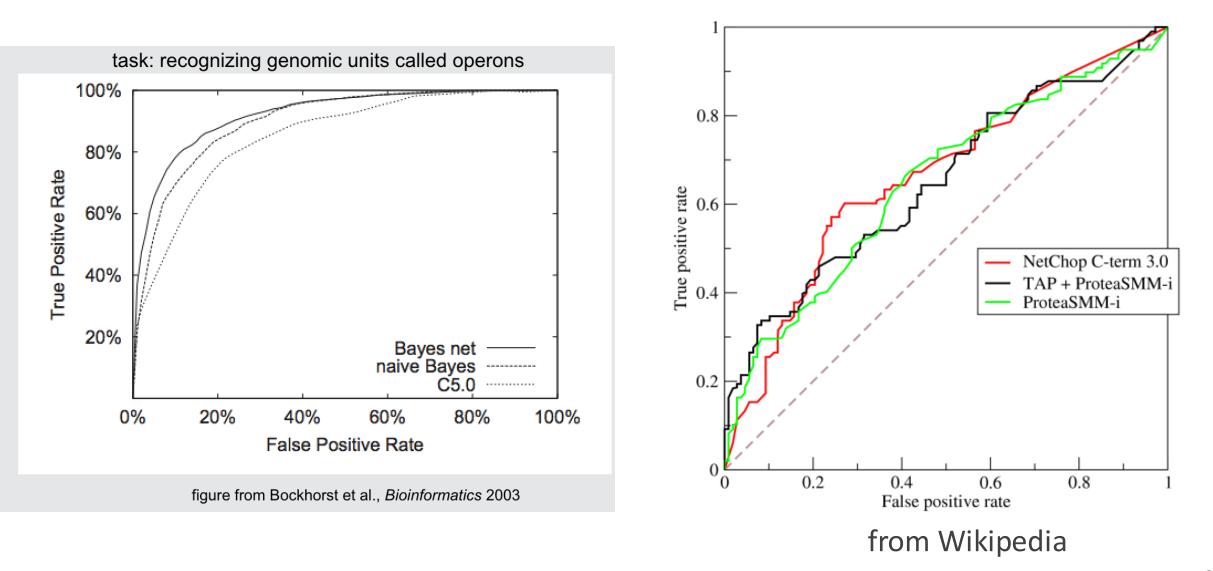
TP = 0, FP = 0

 $last_TP = 0$

for i = 1 to m

// find thresholds where there is a pos instance on high side, neg instance on low side if $(i \ge 1)$ and $(c^{(i)} \ne c^{(i-1)})$ and $(y^{(i)} == neg)$ and $(TP \ge last_TP)$ $\checkmark FPR = FP / num_neg, TPR = TP / num_pos$ output (FPR, TPR) coordinate $last_TP = TP$ if $y^{(i)} == pos$ ++TPelse ++FPFPR = FP / num_neg, TPR = TP / num_pos output (FPR, TPR) coordinate

ROC curve examples



Area under ROC curve

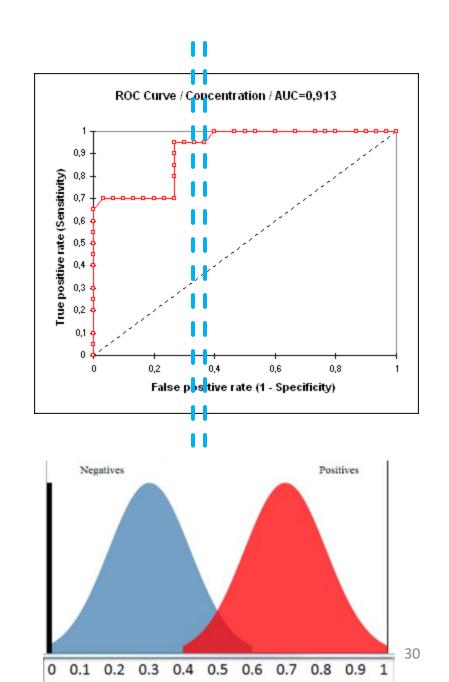
- The boss says "could you just give me one number?"
- **<u>AUC</u>**: Area Under the ROC curve:

AUC(c): =
$$\frac{\sum_{(x_{-},-1)\in S_{-}}\sum_{(x_{+},+1)\in S_{+}}I(c(x_{+})>c(x_{-}))}{N_{-}\cdot N_{+}}$$

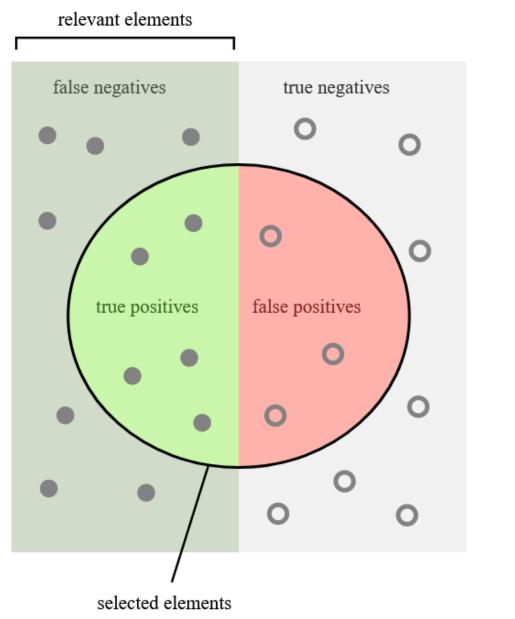
- c(x): decision value of x
- S_- : negative examples, S_+ : positive examples
- Idea: the slice corresponds to x₋ has area

$$\frac{1}{N_{-}} \cdot \frac{\sum_{(x_{+},+1) \in S_{+}} I(c(x_{+}) > c(x_{-}))}{N_{+}}$$

• Interpretation: "how well does *c* distinguish between + and -?"



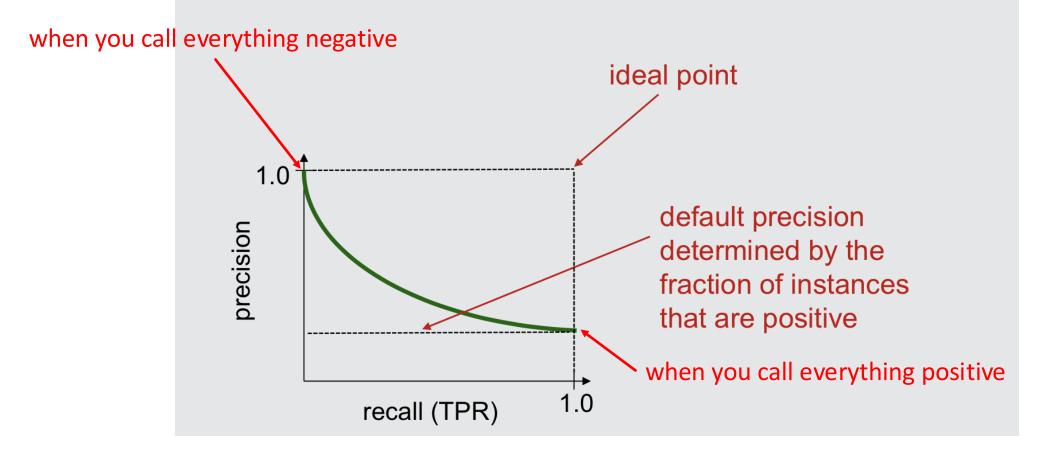
Precision/Recall



Imagine document retrieval system given keyword How many pos'ly-predicted points are actually relevant? **True Positives** Precision = True Positives + False Positives high precision: when it says positive, we can trust it! (but may say 'none is positive') How many positive points are selected? True Positives Recall = True Positives + False Negatives high recall: it does not miss out positive ones! (but may include many negatives) Q: what is a simple way to achieve recall of 1?

Precision-Recall curve

A *precision/recall curve* plots the precision vs. recall (TP-rate) as a threshold on the confidence of an instance being positive is varied



PR-curve example

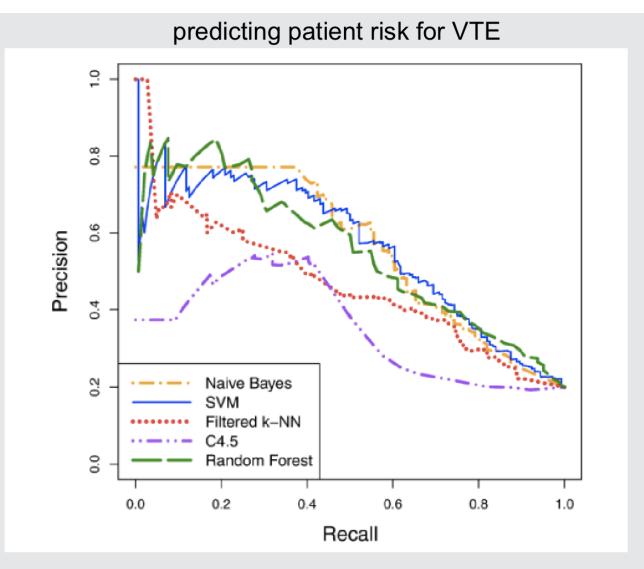


figure from Kawaler et al., Proc. of AMIA Annual Symosium, 2012

Summarizing precision-recall curves

- Reporting one number
- Take the harmonic mean: F1 score
- Recall: minimum of the two <= harmonic mean <= geometric mean <= arithmetic mean

$$F_1 = rac{2}{ ext{recall}^{-1} + ext{precision}^{-1}}$$

- Emphasizes the smaller measure
 - E.g. recall = 0.1, precision = $0.9 \Rightarrow F_1 = 0.18$
- Area under PR-curve is also a popular metric

	0.0	0.2	0.4	0.6	0.8	1.0
0.0	0.00	0.00	0.00	0.00	0.00	0.00
0.2	0.00	0.20	0.26	0.30	0.32	0.33
0.4	0.00	0.26	0.40	0.48	0.53	0.57
0.6	0.00	0.30	0.48	0.60	0.68	0.74
0.8	0.00	0.32	0.53	0.68	0.80	0.88
1.0	0.00	0.33	0.57	0.74	0.88	1.00

Table 5.2: Table of f-measures when varying precision and recall values.

How to plot ROC/PR curve when validation set is small?

- Pooled prediction from k-fold CV.
 - During k-fold CV, do not compute ROC/PR. Just keep the predicted labels.
 - Pretend:
 - The union of the k folds is a single validation set. (each fold was a separate validation set)
 - The predicted labels were from a single classifier (they are from k different classifiers)

The boss says "could you just give me one number?"

- AUC: Area Under the ROC curve
- Literally, this is the size of the area under the ROC curve.
- Surprisingly, there is a closed form solution:

$$AUC(f) = rac{\sum_{t_0 \in \mathcal{D}^0} \sum_{t_1 \in \mathcal{D}^1} \mathbf{1}[f(t_0) < f(t_1)]}{|\mathcal{D}^0| \cdot |\mathcal{D}^1|},$$

- f(x): decision value of x
- D^0 : negative example, D^1 : positive example
- Interpretation: "how well does f distinguish between + and -?"

Hypothesis Testing

Motivation: evaluating & comparing ML models

Example

- Your ML model *f* has test set error = 6.9%
- Your nemesis, Gabe's, ML model *g* has test set error = 6.8%
- How confident are we to conclude that g has smaller generalization error than that of f?
- Intuition: We should be more confident if the test set is larger, less if it's smaller
- Our uncertainty can be quantified with a *confidence interval*
- Determining the best model can be done rigorously with hypothesis testing

Disclaimer: we only focus on the key ideas (standard stats courses spend >= 5 lectures on this)

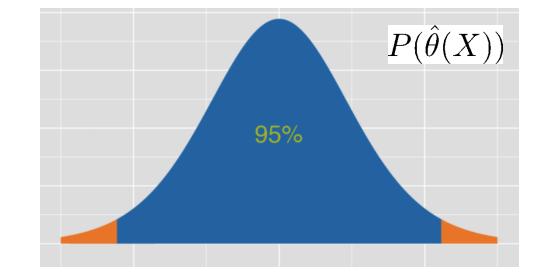
Confidence Intervals

Intuition Find an interval such that we are *pretty sure* it encompasses the true parameter value (e.g. algorithm accuracy).

Given data X_1, \ldots, X_n and confidence $\alpha \in (0, 1)$ find interval (a, b) such that,

 $P(\theta \in (a, b)) \ge 1 - \alpha$

In English the interval (a,b) contains the true parameter value θ with probability at least $1-\alpha$



- Intervals must be computed from data $a(X_1, \ldots, X_n)$ and $b(X_1, \ldots, X_n)$
- Interval (a,b) is random, parameter θ is not random (it is fixed)
- Requires that we know the distribution of the estimator $\hat{ heta}$

Warning

<u>Question</u> How should we interpret a confidence interval (e.g. 95%)?

$P(\theta \in (a(X), b(X))) \ge 0.95$

<u>Hint</u> Think about what is random and what is not...

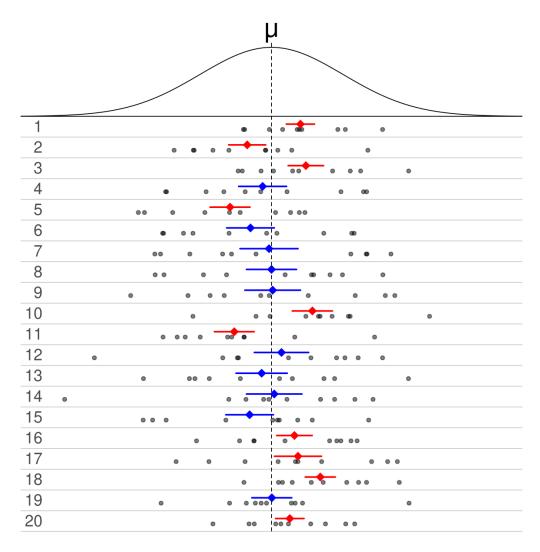
This is NOT a probability statement about θ .

Interpretation

On day 1, you collect data and construct a 95 percent confidence interval for a parameter θ_1 . On day 2, you collect new data and construct a 95 percent confidence interval for an unrelated parameter θ_2 . On day 3, you collect new data and construct a 95 percent confidence interval for an unrelated parameter θ_3 . You continue this way constructing confidence intervals for a sequence of unrelated parameters $\theta_1, \theta_2, \ldots$ Then 95 percent of your intervals will trap the true parameter value. There is no need to introduce the idea of repeating the same experiment over and over.

Knowledge Check

What is the confidence level of this estimator?



Cl construction

A standard recipe:

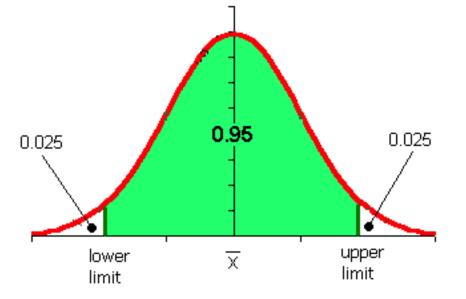
- Construct an estimator for θ based on S -- call it $\hat{\theta}_S$
- Let $I(S) \coloneqq [\hat{\theta}_S w, \hat{\theta}_S + w]$, where w is chosen such that for all θ , $P_{S \sim D_{\theta}^n} (\theta \in [\hat{\theta}_S - w, \hat{\theta}_S + w]) \ge 1 - \alpha$

Important example: confidence interval for normal mean

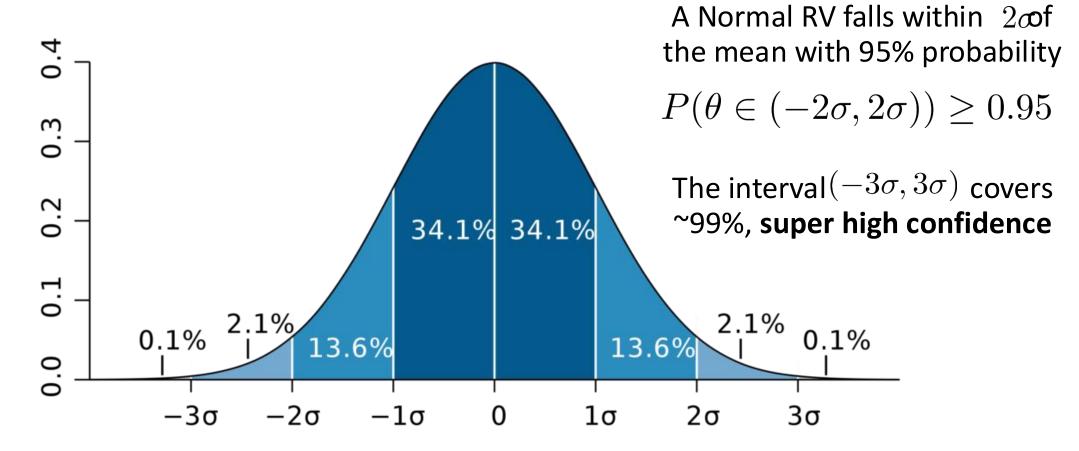
•
$$D_{\mu} = N(\mu, 1), S = (X_1, \dots, X_n) \sim D_{\mu}^n$$

- Define $\hat{\mu}_S = \frac{1}{n} \sum_{i=1}^n X_i$ Known variance
- $\hat{\mu}_S \mu \sim N\left(0, \frac{1}{n}\right)$

• How to choose w such that $P(|\hat{\mu}_S - \mu| \le w) \ge 1 - \alpha$?



Confidence Intervals of the Normal Distribution Given enough data many estimators follow a Normal distribution (central limit theorem)



For various reasons, 95% has become standard confidence level

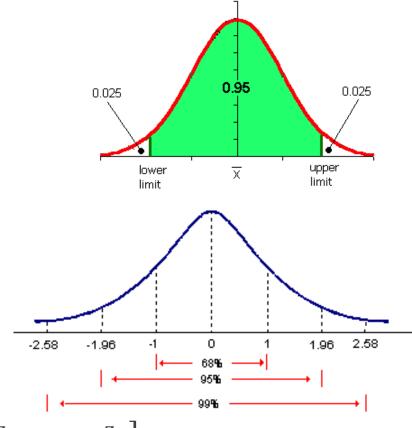
Cl for normal mean (cont'd)

- $\hat{\mu}_S \mu \sim N\left(0, \frac{1}{n}\right)$
- How to choose w such that $P(|\hat{\mu}_S \mu| \le w) \ge 1 \alpha$?

- Note: $Z = \sqrt{n} (\hat{\mu}_S \mu) \sim N(0,1)$ Central limit theorem
- Suffices to find z_{α} such that $P(|Z| \le z_{\alpha}) \ge 1 \alpha$, and let $w = \frac{z_{\alpha}}{\sqrt{n}}$

• Final $(1 - \alpha)$ -confidence interval construction for $\mu: I(S) = \left[\hat{\mu}_S - \frac{z_\alpha}{\sqrt{n}}, \hat{\mu}_S + \frac{z_\alpha}{\sqrt{n}}\right]$

• E.g. 95%-confidence interval for $\mu: I(S) = \left[\hat{\mu}_S - \frac{1.96}{\sqrt{n}}, \hat{\mu}_S + \frac{1.96}{\sqrt{n}}\right]$



CI for means of general distributions, unknown variance

- Given D_{θ} with mean parameter θ with *unknown* variance
- $\hat{\sigma}_n^2 \coloneqq \frac{\sum_{i=1}^n (X_i \hat{\mu}_n)^2}{n-1} \Longrightarrow$ unbiased estimator of $var(D_\theta)$
- Theorem: Let $X_1, ..., X_n \sim N(\mu, \sigma^2)$, and $\hat{\mu}_n \coloneqq \frac{1}{n} \sum_{i=1}^n X_i$

$$\sqrt{n} \frac{\hat{\mu}_n - \mu}{\hat{\sigma}_n} \sim \text{student-t} \text{ (mean 0, scale 1, degrees of freedom = } n - 1\text{)}$$

import scipy.stats as st alpha = 0.05 st.t.ppf(1-alpha/2,df=2) => 4.302652729911275

st.t.ppf(1-alpha/2,df=5) => 2.5705818366147395

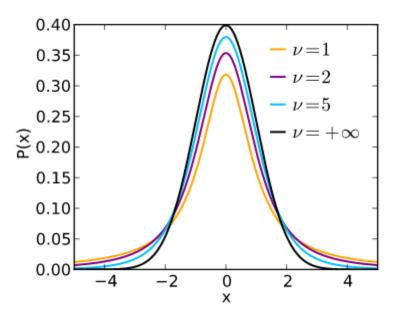
st.t.ppf(1-alpha/2,df=10) => 2.2281388519649385

st.t.ppf(1-alpha/2,df=30) => 2.0422724563012373

st.t.ppf(1-alpha/2,df=100) => 1.9839715184496334

How do we estimate variance of algorithm performance?

• CI: $\left| \hat{\mu}_n \pm \frac{\hat{\sigma}_n \cdot t_{\alpha}}{\sqrt{n}} \right|$



Bootstrap Example

Example Suppose we have LSAT scores and GPA for 15 law students and wish to estimate the correlation between LSAT and GPA:

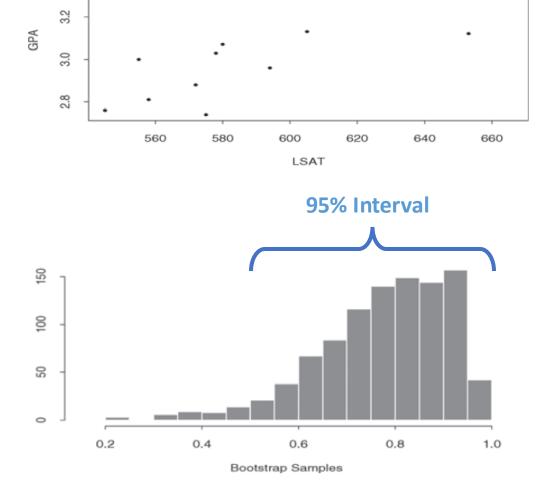
3.4

LSAT	576	635	558	578	666	580	555	661
	651	605	653	575	545	572	594	
GPA	3.39	3.30	2.81	3.03	3.44	3.07	3.00	3.43
	3.36	3.13	3.12	2.74	2.76	2.88	3.96	

95% Bootstrap confidence interval from B=1000 estimates of the **correlation**,

 $.78 \pm .274 \Rightarrow (.51, 1.00)$

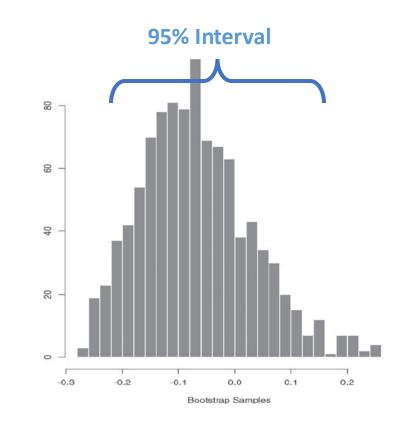
Q Should we trust this confidence interval? Why or why not?



[Source: Wasserman, L. 2004]

Bootstrap Example Eight subjects who used medical patches to infuse a hormone into the blood using three treatments: placebo, old-patch, new-patch

subject	placebo	old	new	old $-$ placebo	new - old
1	9243	17649	16449	8406	-1200
2	9671	12013	14614	2342	2601
3	11792	19979	17274	8187	-2705
4	13357	21816	23798	8459	1982
5	9055	13850	12560	4795	-1290
6	6290	9806	10157	3516	351
7	12412	17208	16570	4796	-638
8	18806	29044	26325	10238	-2719



Estimate whether relative efficacy is the same under new drug,

$$\theta = \frac{\mathbf{E}[\text{new} - \text{old}]}{\mathbf{E}[\text{old} - \text{placebo}]}$$

Bootstrap B=1,000 samples yields 95% confidence interval,

 $\theta \in (-0.24, 0.15)$

Q Is this more trustworthy than in previous example?

Bootstrapping Cl

<u>empirical distribution</u> of $\{X_1, ..., X_n\}$: $\frac{1}{n}\sum_{i=1}^n \delta_{X_i}$ where δ_X is a dirac delta function

- Goal: estimate property h of D (:=h(D)) using confidence intervals, using sample S (e.g. h=F1 of model f)
- Idea: estimate the distribution of h(S) h(D), denoted by R_h

by bootstrapping (resampling)

- perform n times of "sampling with replacement" from S
- repeat *B* times (e.g., $B \approx 10^4$) to obtain S_1, \dots, S_B
- take $\nu \coloneqq \underline{\text{empirical distribution}}$ of $\{h(S_b) h(S)\}_{b=1}^B$, as the <u>'shape'</u> of R_h
- Assumption: $h(S) h(D) \sim R_h \approx \text{emp}_distribution} [\{h(S_b) h(S)\}_{b=1}^B]$

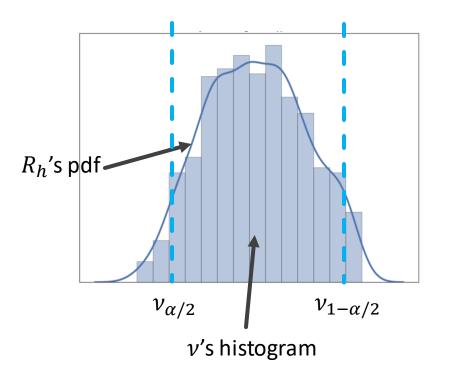
 R_h 's pdf of R_h $v_{\alpha/2}$ $v_{1-\alpha/2}$ v's histogram

Quantile interval: sort values and take top/bottom-quantiles (see next slide)

• With prob. $\approx 1 - \alpha$, $h(S) - h(D) \in [\nu_{\alpha/2}, \nu_{1-\alpha/2}] \Longrightarrow I(S) = [h(S) - \nu_{1-\alpha/2}, h(S) - \nu_{\alpha/2}]$

Bootstrapping CI: Implementation

- From bootstrapping, obtain ${h(S_b) h(S)}_{b=1}^B$
- How to calculate its empirical distribution's quantiles?
 - Sort them in increasing order; say v[0..(B-1)]
 - $v_{1-\alpha/2} \coloneqq$ the top 0.025 (i.e., v[int(0.975*B)])
 - $v_{\alpha/2}$:= the bottom 0.025 (i.e., v[int(0.025*B)])



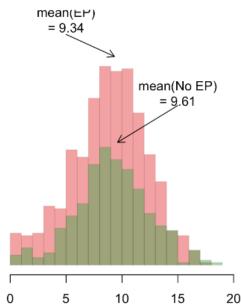
Hypothesis testing: motivation

- How to claim your new system A is better than existing one B
- Ex1: each test data point => take prediction from A & B => record correct/not
- Ex2: each evaluator => a random keyword is picked, and then both systems pick top 10 relevant documents and rank them => the evaluator provides rating (1-5) for both lists.

Evaluator	1	2	3	4	5	6	
А	5	2	2	5	4	2	
В	4	1	1	4	3	1	

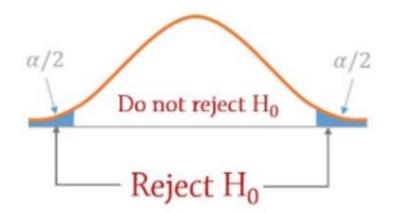
Two-sample hypothesis testing: definition

- Given D_{θ} with parameter θ
- Samples $S_X = (X_1, ..., X_n)$ and $S_Y = (Y_1, ..., Y_n)$ drawn iid from distribution D_{θ_X} and D_{θ_Y} , respectively
- Equality test version:
 - Null hypothesis $H_0: \theta_X = \theta_Y$
 - Alternative hypothesis $H_1: \theta_X \neq \theta_Y$
- E.g. $D_{\mu} = \text{Ber}(\mu), H_0: \mu_X = \mu_Y$
- Similarly, design hypothesis tester T such that the two types of errors are controlled



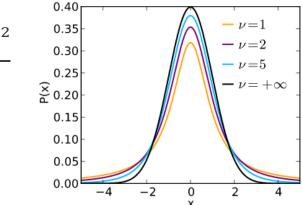
Paired t-test

- $S_X = (X_1, ..., X_n)$ and $S_Y = (Y_1, ..., Y_n)$ drawn iid from distribution $D_{\theta_X} = N(\mu_X, \sigma_X^2)$ and $D_{\theta_Y} = N(\mu_Y, \sigma_Y^2)$, respectively
 - $H_0: \mu_X = \mu_Y$
 - $H_1: \mu_X \neq \mu_Y$
- Let $\delta_i \coloneqq X_i Y_i$, for all i = 1, ..., n
- Let $\overline{\delta}_n \coloneqq \frac{1}{n} \sum_{i=1}^n \delta_i$
- Design hypothesis test T so that $P_{H_0}(T(S) = 0) \ge 1 \alpha$
- Intuition: reasonable to reject if $|\bar{\delta}_n|$ is large



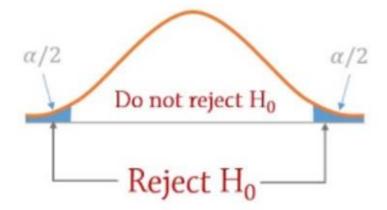
Paired t-test

- Under H_0 , $\delta_i \sim N(0, \sigma^2)$, i = 1, ..., n, where $\sigma^2 = \sigma_X^2 + \sigma_Y^2$
- Recall Thm: Let $\delta_1, ..., \delta_n \sim N(0, \sigma^2)$, and $\overline{\delta}_n \coloneqq \frac{1}{n} \sum_{i=1}^n \delta_i$, $\widehat{\sigma}_n^2 \coloneqq \frac{\sum_{i=1}^n (\delta_i \overline{\delta}_n)^2}{n-1}$ $Z = \sqrt{n} \frac{\overline{\delta}_n}{\widehat{\sigma}_n} \sim \text{student-t} \text{ (mean 0, scale 1, degrees of freedom = } n-1\text{)}$



- Let's ask "under H_0 , what is a plausible range of values of Z with failure rate $\alpha = 0.05$?"
 - Find the 0.025, 0.975-quantiles of $Z \Rightarrow t_{0.025}, t_{0.975}$
 - Hypothesis tester

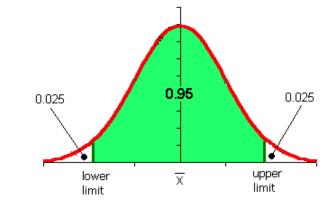
$$T(S) = I(Z \notin [t_{0.025}, t_{0.975}]) = I\left(\sqrt{n}\frac{\bar{\delta}_n}{\hat{\sigma}_n} \notin [t_{0.025}, t_{0.975}]\right)$$

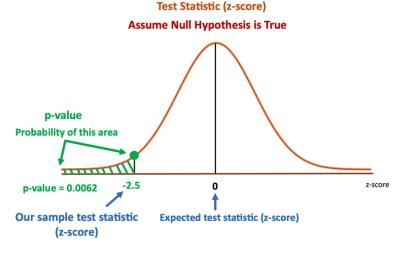


Hypothesis testing: additional remarks

- Confidence intervals can be used for hypothesis testing
 - $S = (X_1, ..., X_n)$ drawn iid from distribution D_{μ}
 - $H_0: \mu = 0$
 - $H_1: \mu \neq 0$
 - *I* is a (1α) -Cl construction for $\mu =>$ hypothesis test $T(S) = I(0 \notin I(S))$ has significance α
- p-value: given dataset S, and a family of hypothesis tests T_{α} 's with different significance α 's

p = the smallest α with which you can still reject H_0

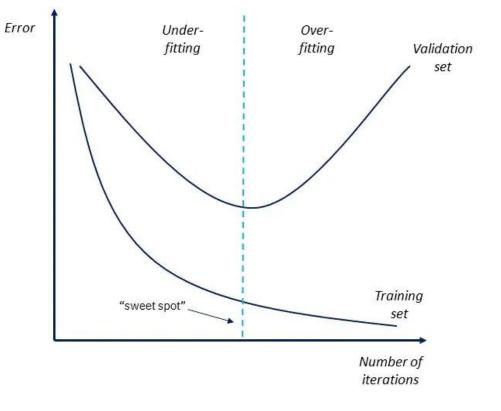




Sampling Distribution of

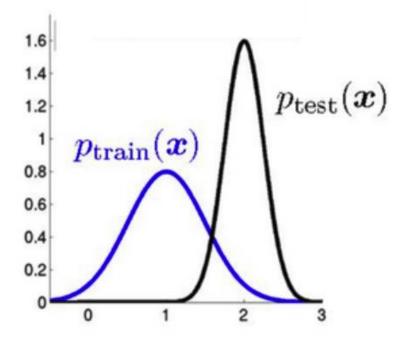
Is the problem with generalization to test data?

- Is it doing well on training?
- Unrealistic to do better on test than on training
- If it does well on training then problem is *generalization*
- Model may be too complicated (overfitting)
- Too many features, not enough training data
- Otherwise, problem may be *representation* : need better features or better data



Is there a mismatch between training and test?

- Training data may be inadequate
- Do results change with different train / test split?
- If so then test distribution is probably strange
- Otherwise you have other generalization problems...



Is the learning algorithm implemented correctly?

- Is it optimizing the loss function that you intended?
- Try measuring / visualizing your loss function during training-is it going down?
- Do the data meet your algorithmic assumptions?
- Hand-craft datasets where you know the desired behavior
 - KNN on XOR function
 - Perceptron on data that is trivially linearly-separable (y=x+1 and y=x-1)
 - Decision tree on axis-aligned data
 - Generally, create dataset that meets assumptions of your algorithm

Do you have adequate representation?

- Your feature set could be inadequate
- For binary classification try this...
 - Add a feature (maybe call it CheatingIsFun)
 - Set value to +1 for positive instances and -1 for negative instances
 - This feature is a *perfect indicator*-problem is now trivially solvable
 - Does your algorithm solve it?
- If your algorithm doesn't get near 0% error then you *may* have a bug! (or more data / less features)
- If it does then you need better features or a different model (e.g. decision tree vs. linear model)

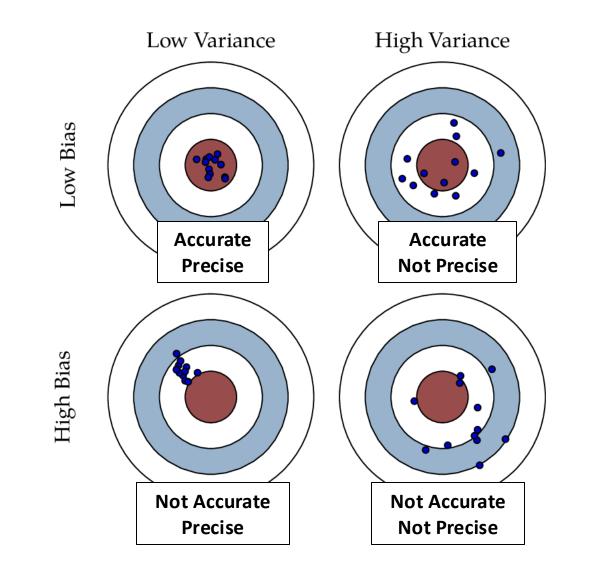
Do you have enough data?

- Always have at least as many training data as you have learnable model parameters
- Try training on 80% of your training data
 - Does performance suffer?
 - How much? A lot?
 - If so then getting more data is likely helpful
 - If not then you may be *data saturated*-look elsewhere
- More training data should never lead to worse performance (just slower training)

Bias / Variance Tradeoff

Bias-Variance Tradeoff

Suppose an archer takes multiple shots at a target...



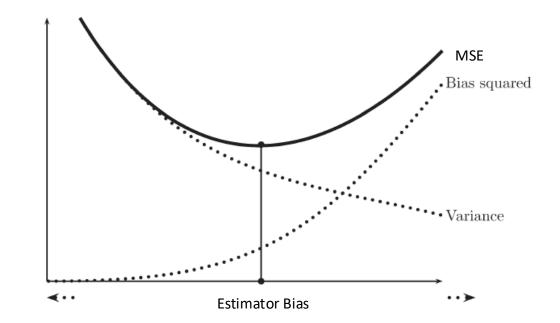
Bias-Variance Tradeoff

Is an unbiased estimator "better" than a biased one? It depends...

Evaluate the quality of estimate $\hat{\theta}$ using **mean squared error**,

$$MSE(\hat{\theta}) = \mathbf{E}\left[(\hat{\theta} - \theta)^2\right] = bias^2(\hat{\theta}) + \mathbf{Var}(\hat{\theta})$$

- MSE for unbiased estimators is just, $\mathrm{MSE}(\hat{\theta}) = \mathbf{Var}(\hat{\theta})$
- Bias-variance is fundamental tradeoff in statistical estimation
- MSE increases as **square** of bias
- Estimators with small bias (but low variance) can have lower MSE than unbiased estimators



Bias-Variance Decomposition

$$\begin{split} \text{MSE}(\hat{\theta}) &= \mathbf{E} \left[(\hat{\theta}(X) - \theta)^2 \right] \\ &= \mathbf{E} \left[\left(\hat{\theta} - \mathbf{E}[\hat{\theta}] + \mathbf{E}[\hat{\theta}] - \theta \right)^2 \right] \\ &= \mathbf{E}[(\hat{\theta} - \mathbf{E}[\hat{\theta}])^2] + 2(\mathbf{E}[\hat{\theta}] - \theta)\mathbf{E}[\hat{\theta} - \mathbf{E}[\hat{\theta}]] + \mathbf{E}[(\mathbf{E}[\hat{\theta}] - \theta)^2] \\ &= \mathbf{E}[(\hat{\theta} - \mathbf{E}[\hat{\theta}])^2] + \left(\mathbf{E}[\hat{\theta}] - \theta \right)^2 \\ &= \text{Var}(\hat{\theta}) + \text{bias}^2(\hat{\theta}) \end{split}$$

Other materials

- Bootstrap test: <u>https://ocw.mit.edu/courses/mathematics/18-05-introduction-to-probability-and-statistics-spring-2014/readings/MIT18_05S14_Reading24.pdf</u>
- Permutation test: <u>https://www.jwilber.me/permutationtest/</u>
- STAT 566 lecture slides (at UA): <u>https://www.math.arizona.edu/~jwatkins/stat566s20s.html</u>

Next lecture (9/19)

- Linear models revisited: classification, regression, loss minimization formulations
- Assigned reading: CIML Chapter 7
- Note: We are skipping Chapter 6 for now!