



Computer
Science



CSC535: Probabilistic Graphical Models



Course Wrap-Up

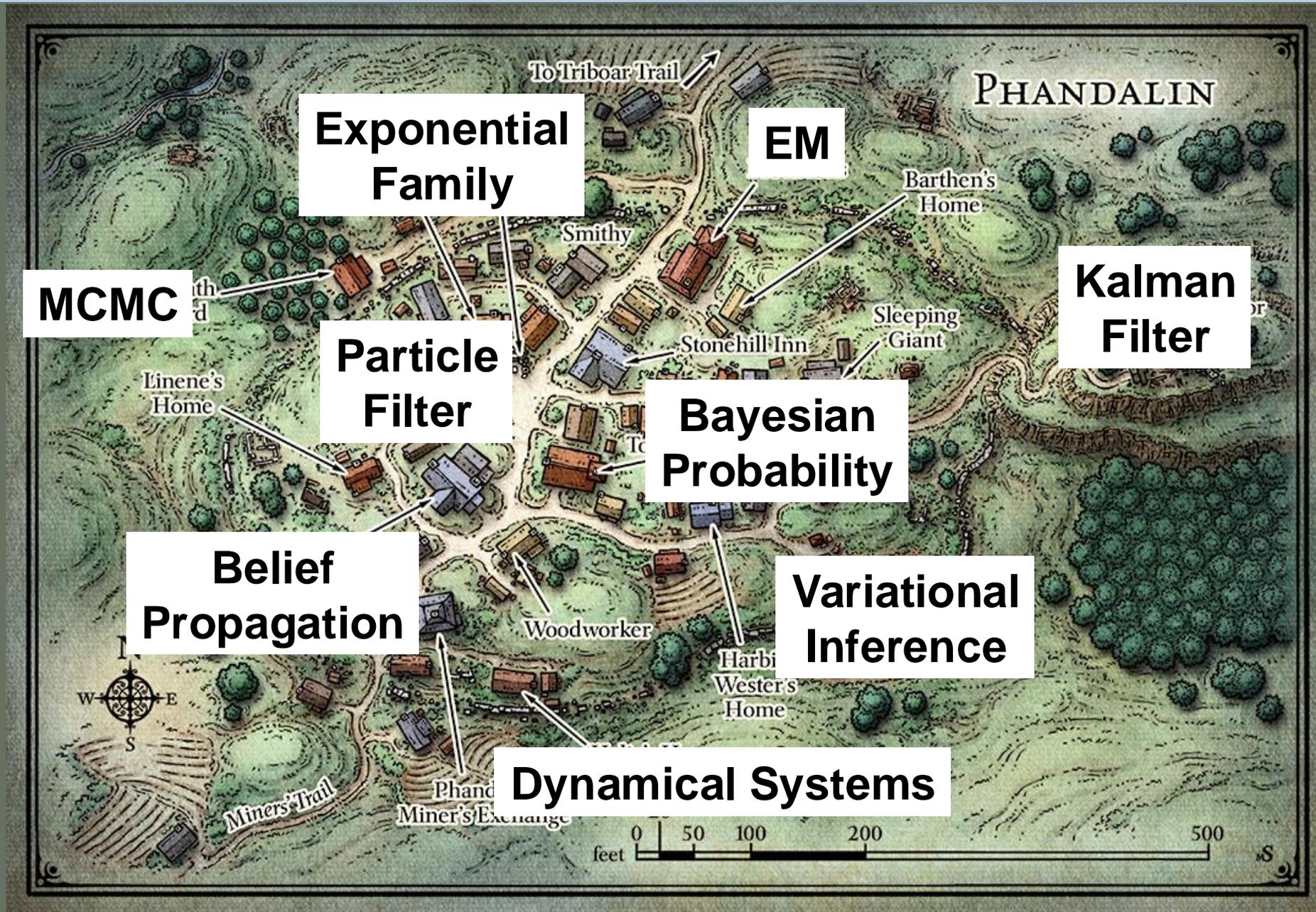
Prof. Jason Pacheco



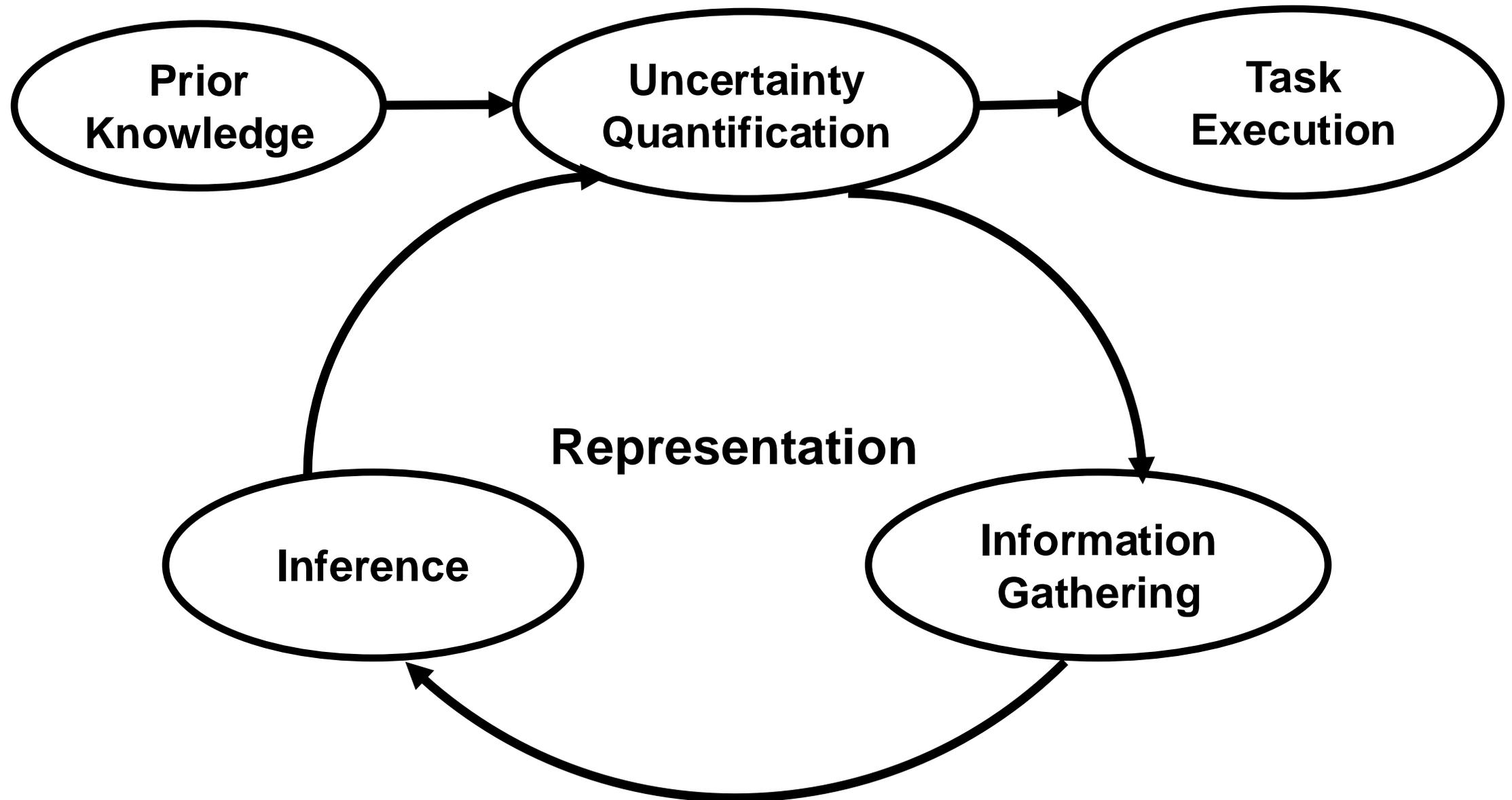
What we covered...

Probability and Statistics	Message Passing Algorithms	Monte Carlo Methods	Sequence Models and Dynamical Systems	Variational Inference	Bayesian Deep Learning
Probability primer, Bayesian statistics, PGMs, Exponential families	Elimination, Junction tree, Sum-product / max-product, Belief propagation, Viterbi decoding	Rejection sampling, Importance sampling, Metropolis-Hastings, Gibbs	Linear and switching state-space models, Kalman filter, Particle filter	Mean field, Stochastic variational, Bethe energy methods	Combining probability and deep learning models

Roadmap for ML Practice & Research

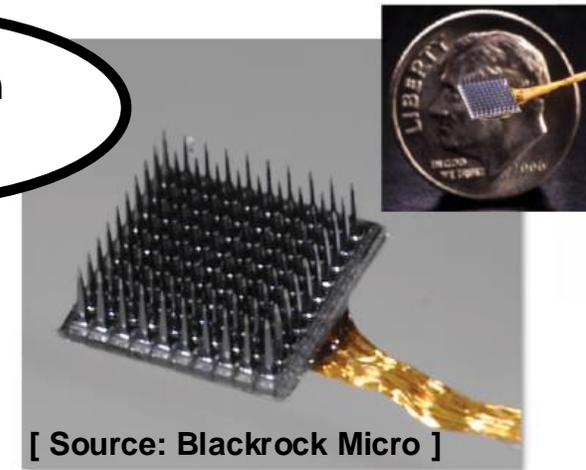
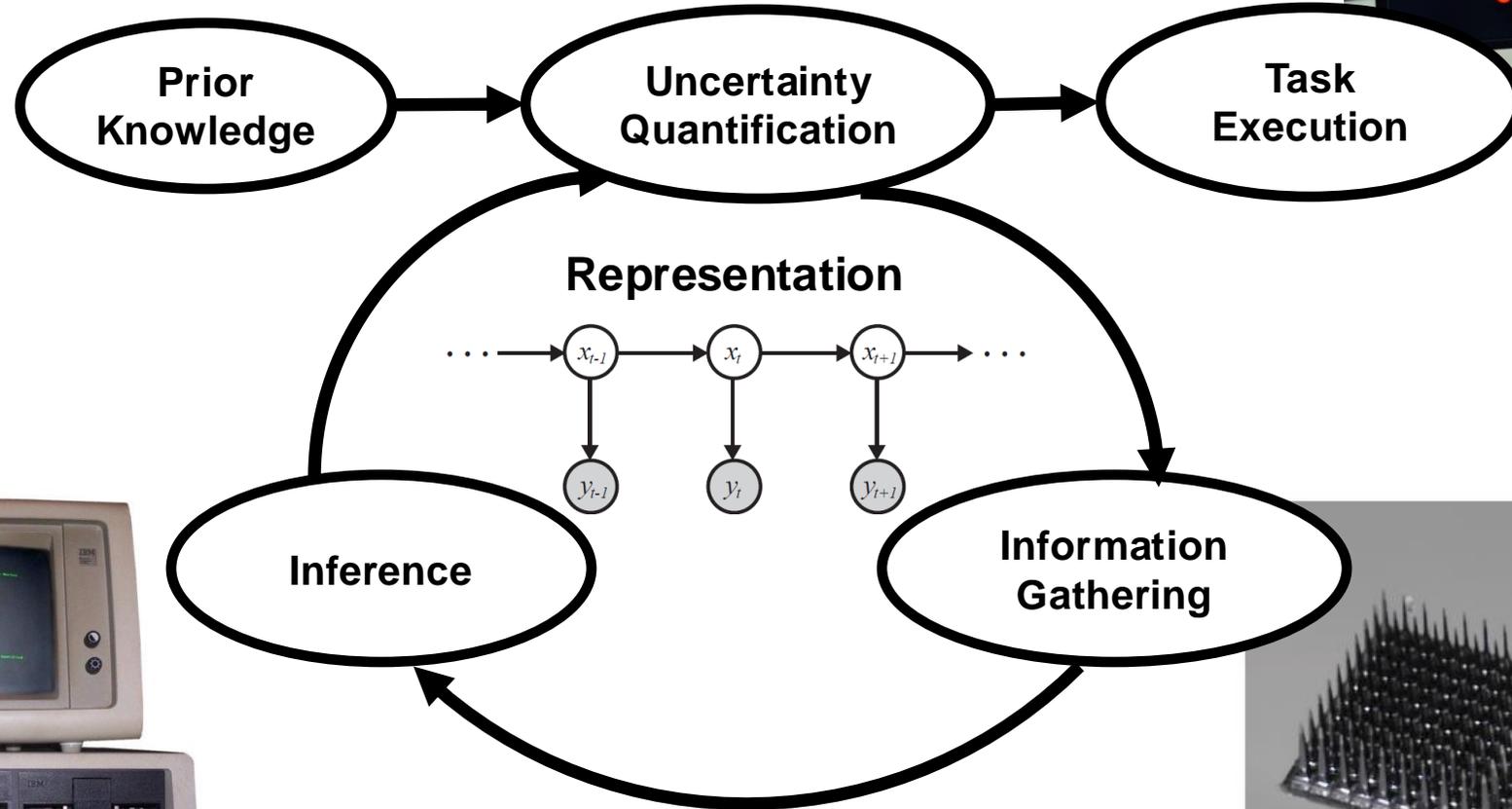
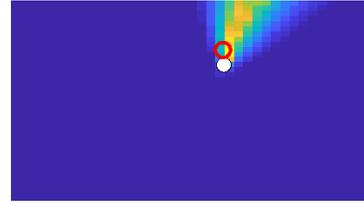
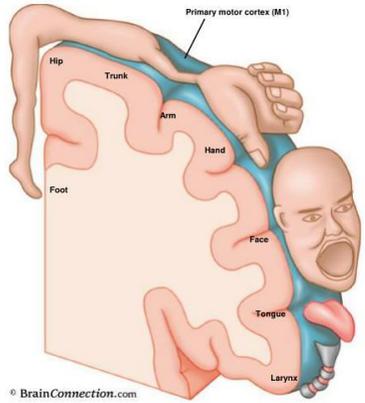


Probabilistic Reasoning

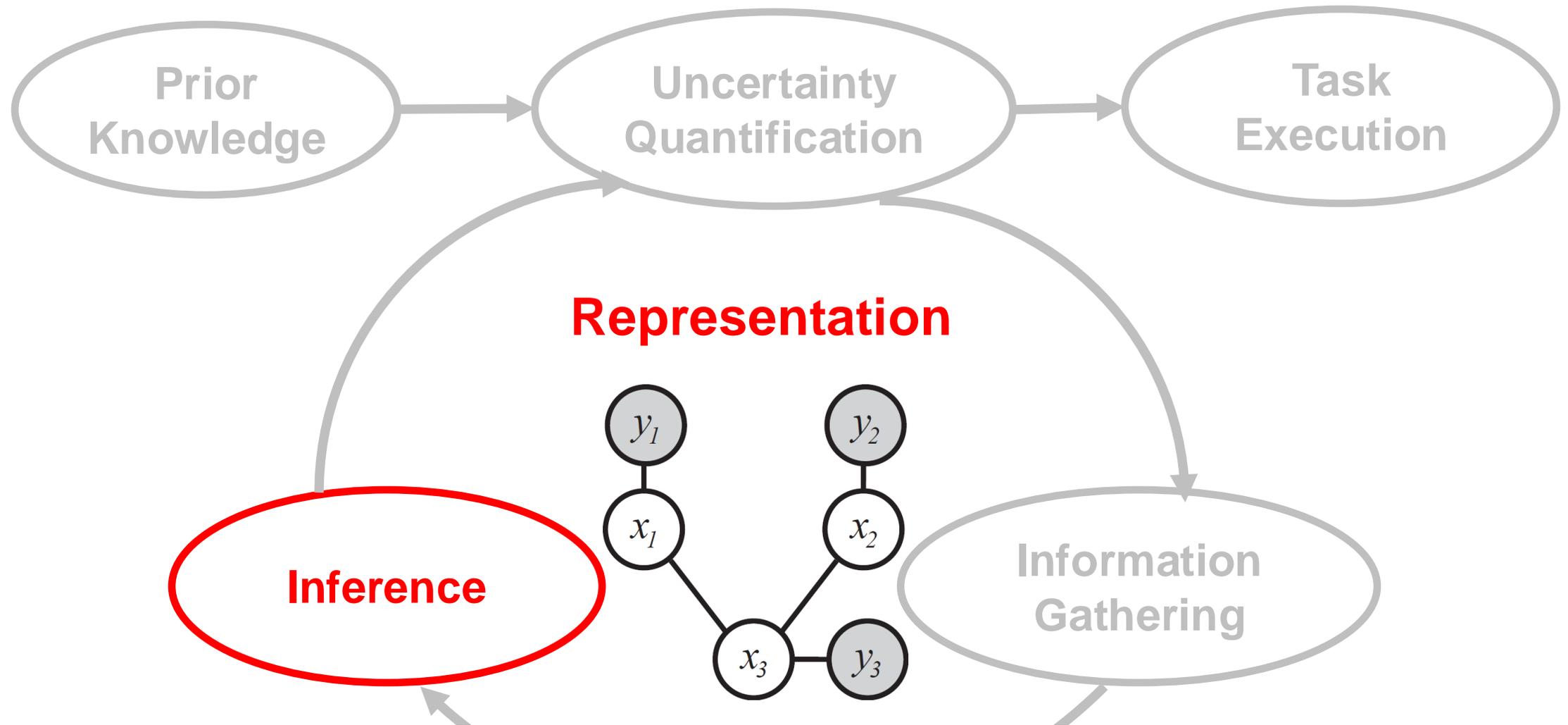


Block 12: "Multiscale Semi-Markov Model"

Probabilistic Reasoning



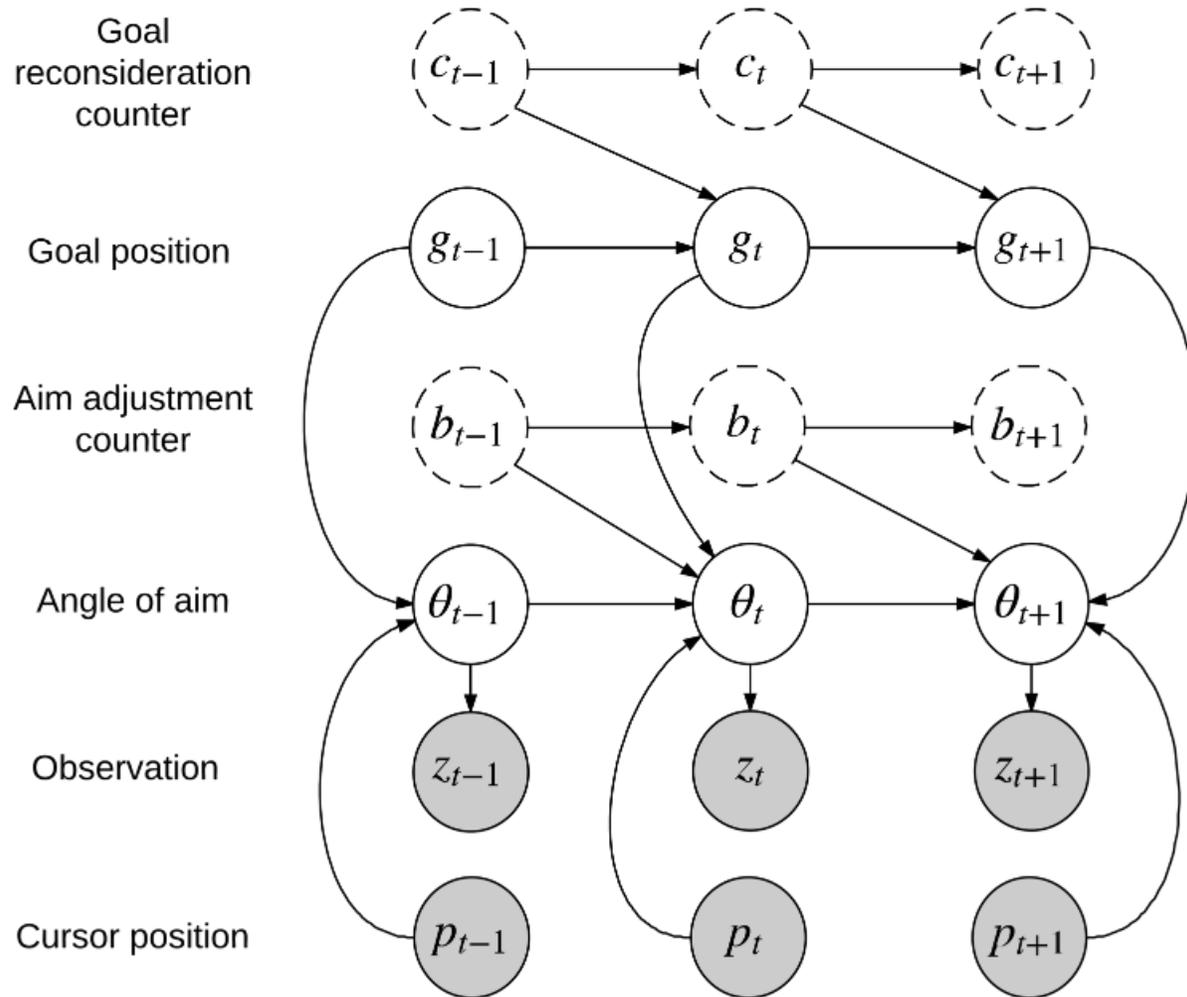
Probabilistic Reasoning



Facilitates development of efficient inference algorithms.

Intracortical Brain-Computer Interfaces (iBCI)

Multiscale Semi-Markov Model



Block 12: "Multiscale Semi-Markov Model"

Goal Given observed neural activity and cursor position infer user intended motion of cursor and goal location.

$$p(\theta_t, g_t \mid z_1^t, p_1^t)$$

Marginal Posterior

Observe Each model component sufficiently low-dimensional to discretize.

Approach Compute discrete BP messages

iBCI : MSSM vs. Kalman Filter

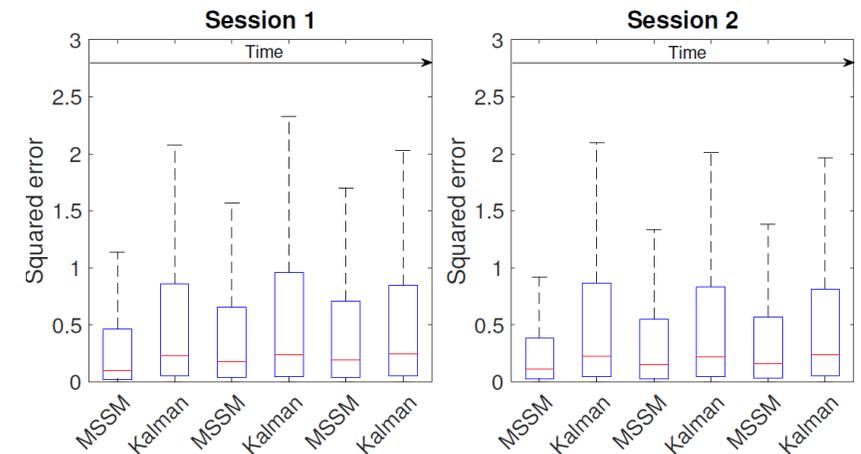
Multiscale Semi-Markov Model (MSSM)

Block 12: "Multiscale Semi-Markov Model"

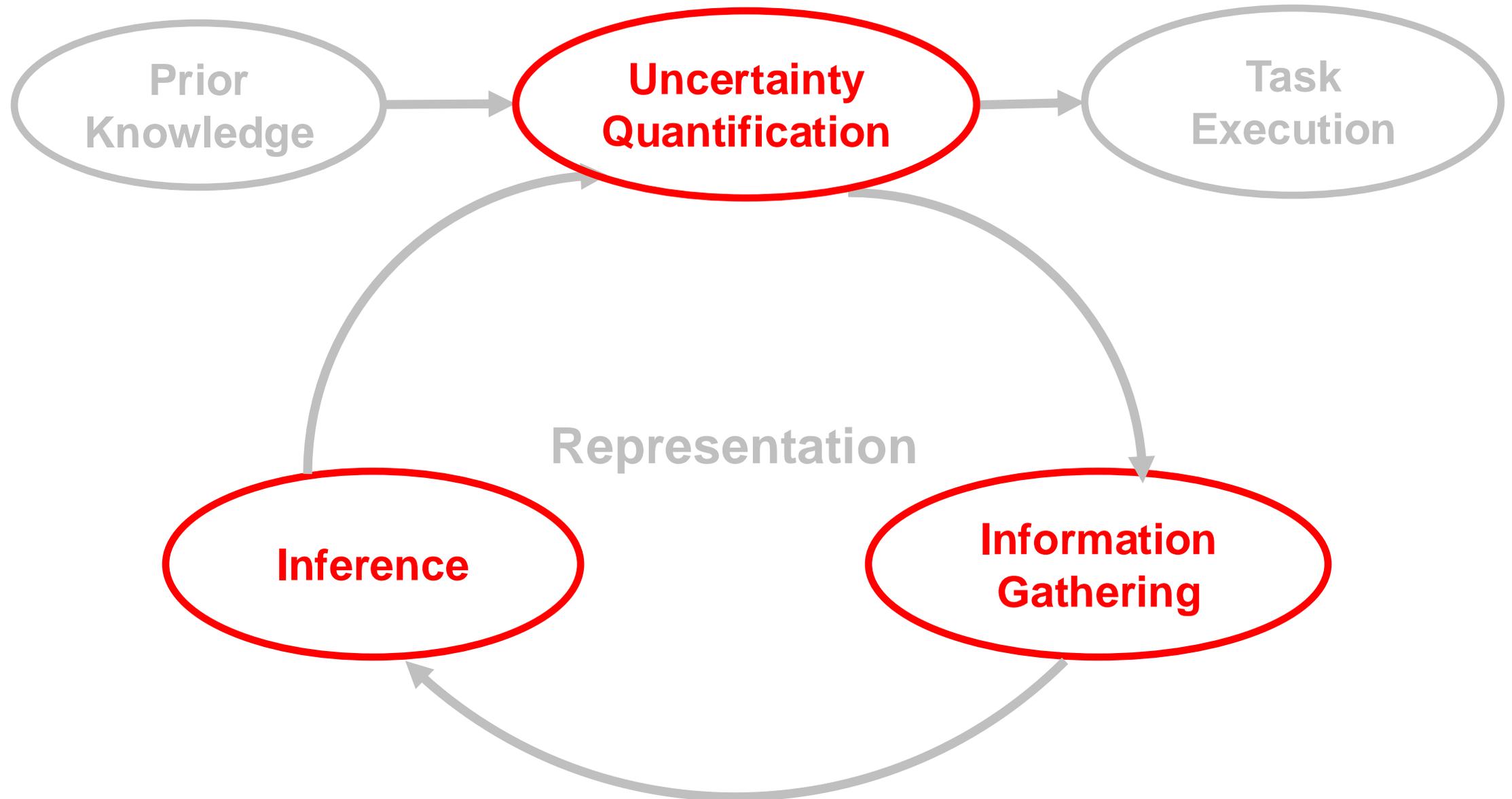
- Allows modelling of nonlinear / non-Gaussian dynamics
- **Dependency structure allows for discretization of each random variable**
- Discrete approximation belief propagation meets real-time constraints

Linear Gaussian (Kalman Filter)

Block 13: "Kalman filter"



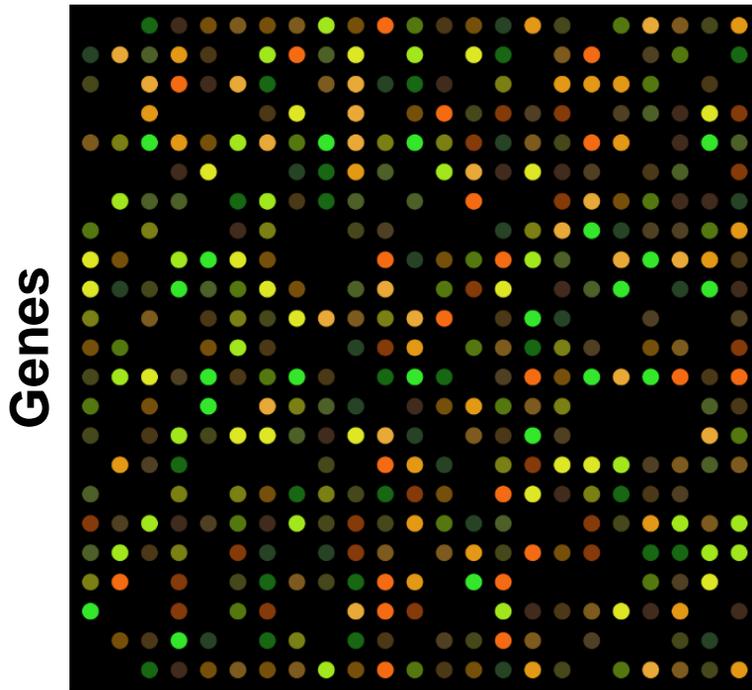
Probabilistic Reasoning



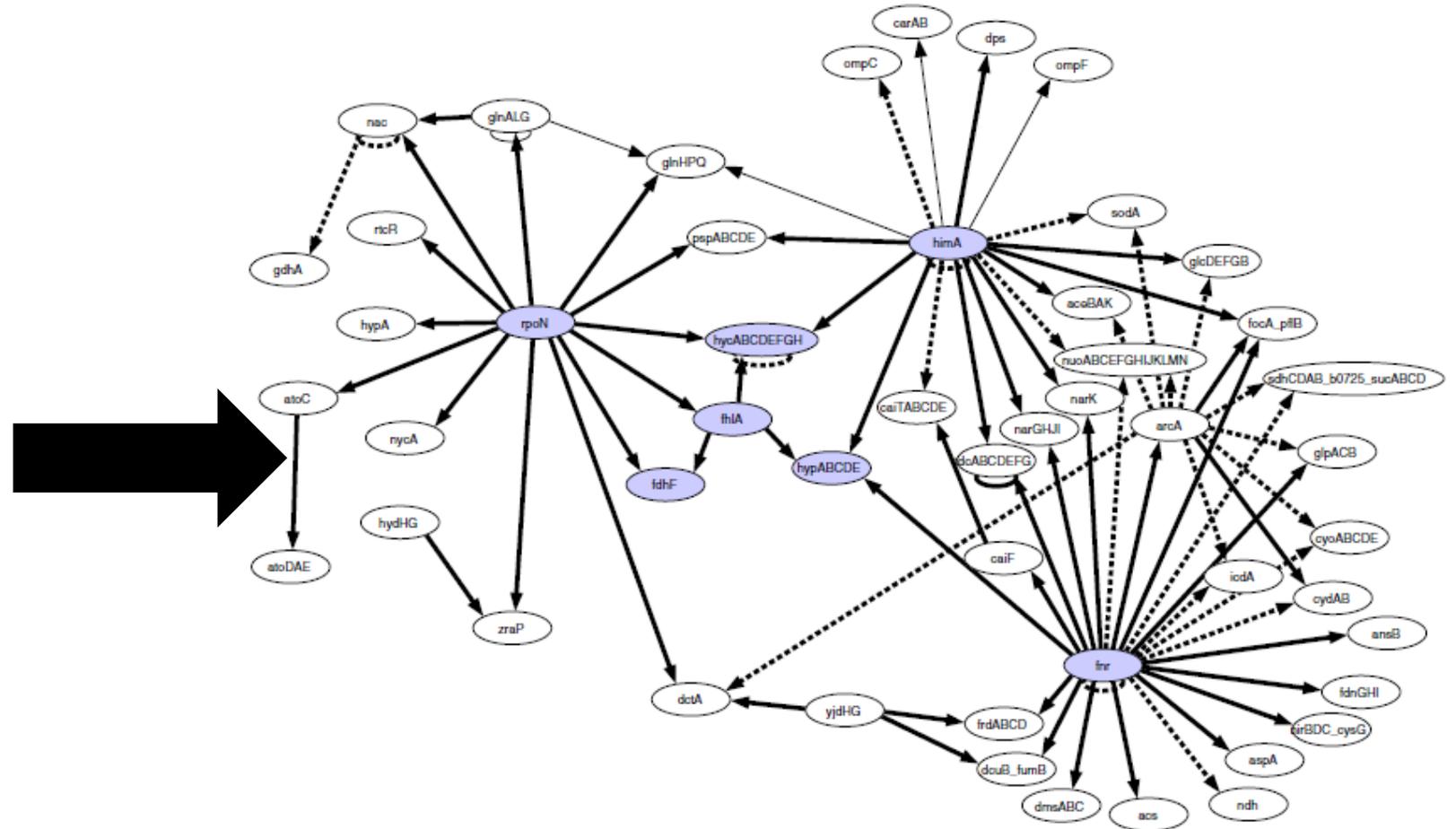
Example: Gene Regulatory Network

Gene Expression

Genes



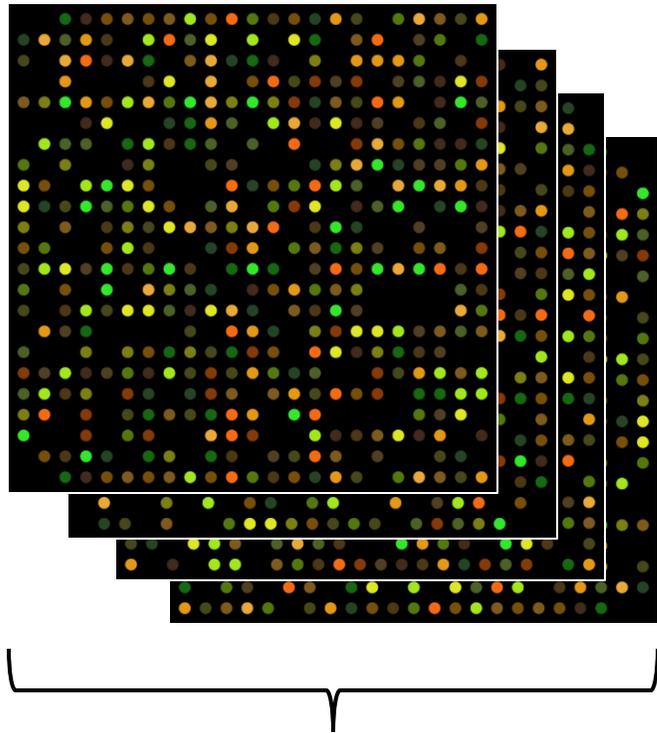
Regulatory Network



Goal: Estimate causal interaction network from expression data.

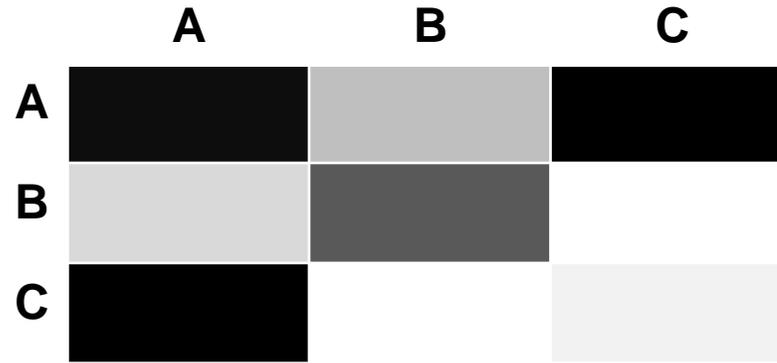
[Image: Bulcke et al., 2006]

Identifying Causality

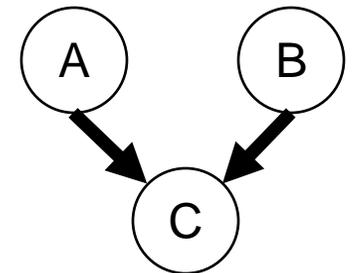
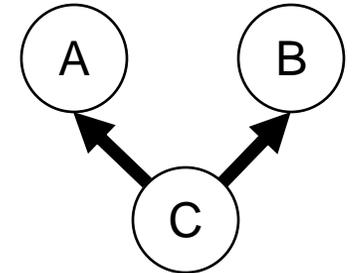
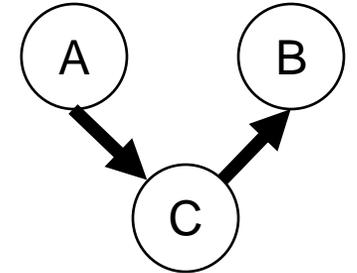


Dataset

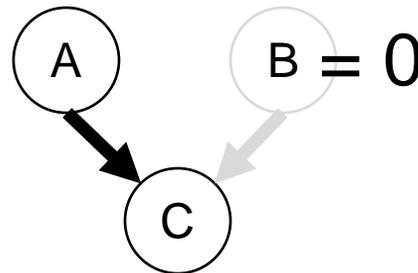
Covariance Matrix



Possible Graphs



Cannot determine causality from correlations, need to perform active interventions ...

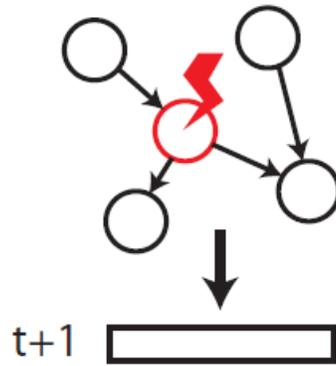


Clamp node to fixed value.

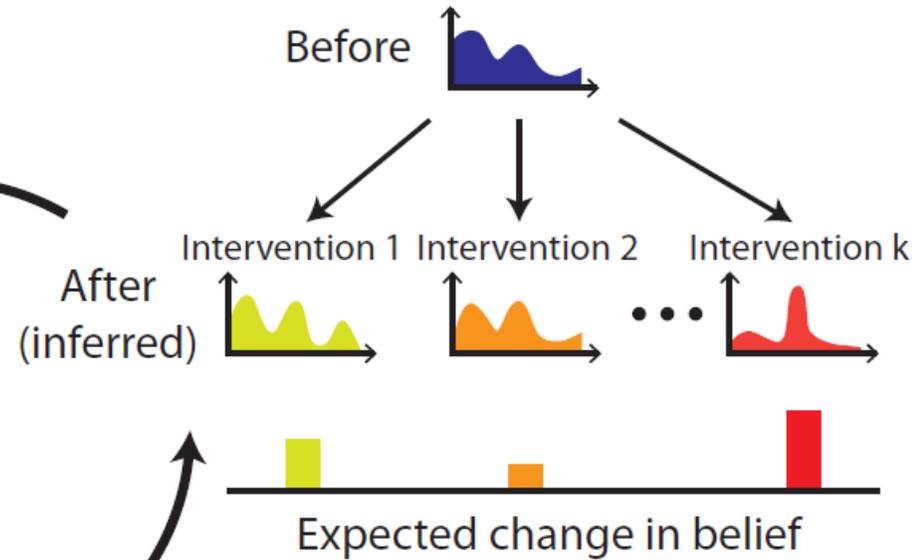
Gene Knockout

Bayesian Optimal Experiment Design

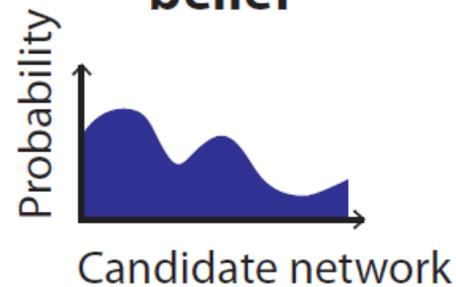
Perform optimal intervention



Evaluate candidate interventions

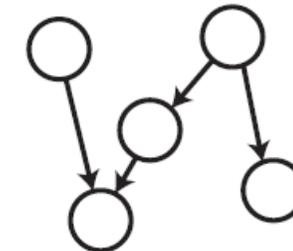


Calculate/update belief

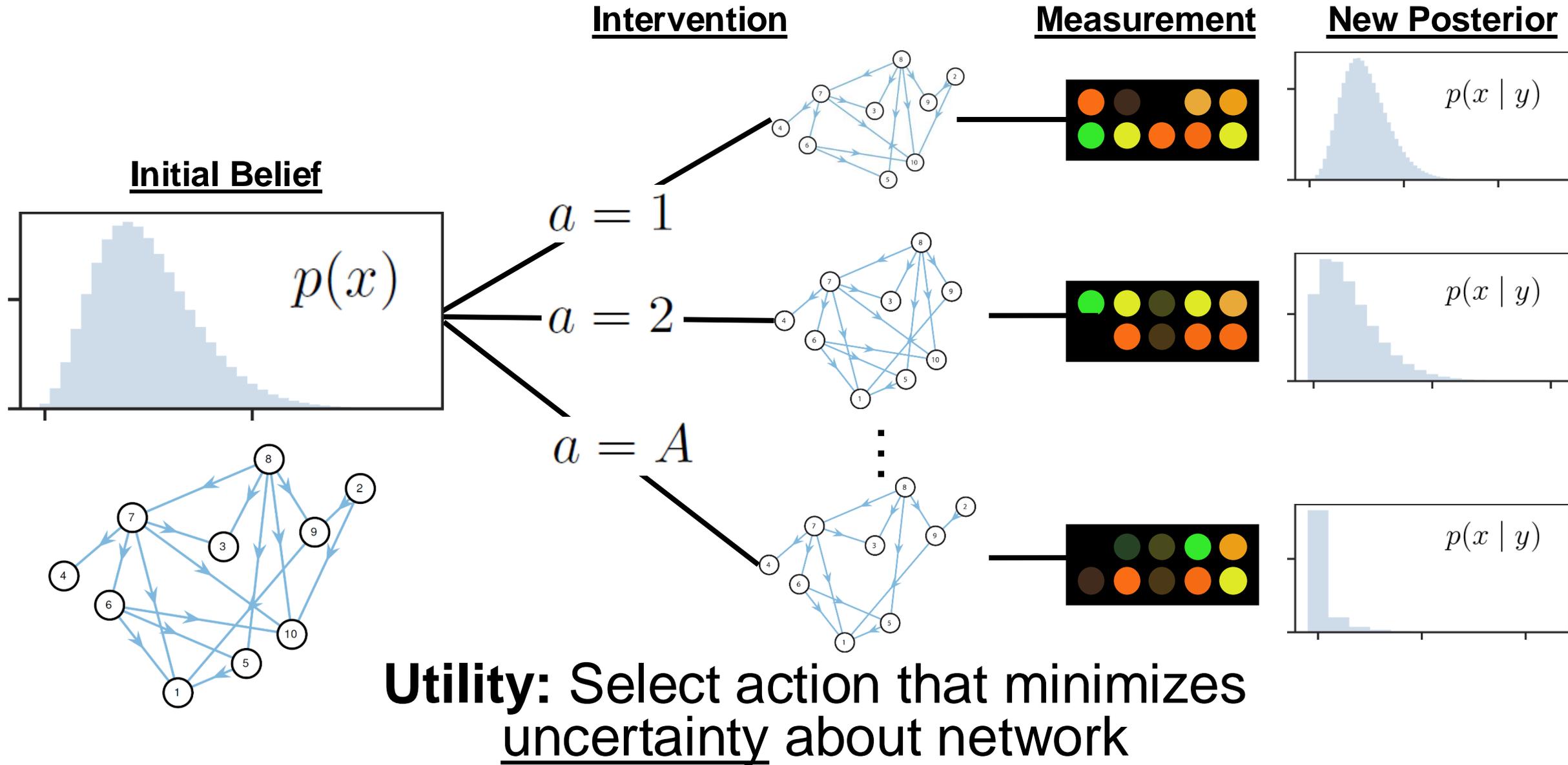


Model averaging

Reconstructed network



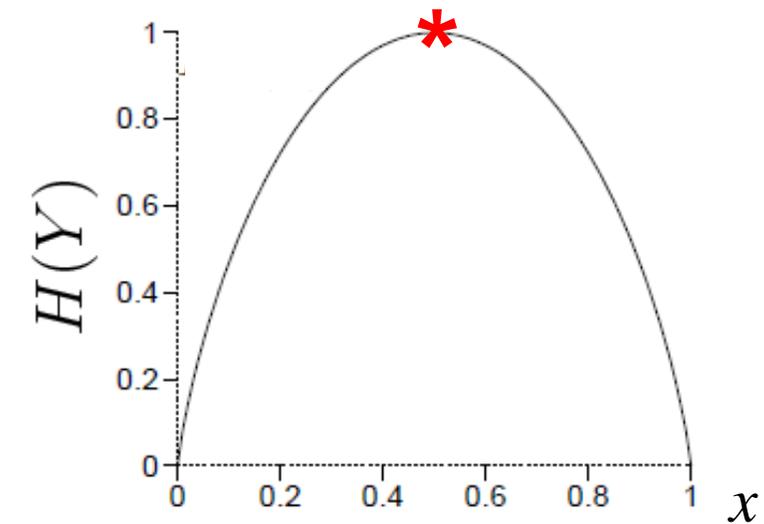
Choosing Actions



Uncertainty and Information

$$H(Y) = \mathbb{E}[-\log p(Y)]$$

Coin Flip Example: $Y \sim \text{Bernoulli}(x)$

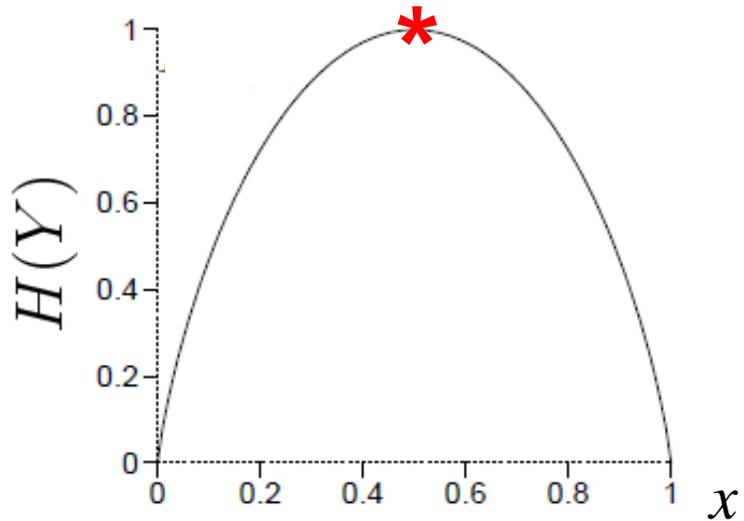


Maximum uncertainty when coin is fair.

Uncertainty and Information

$$H(Y) = \mathbb{E}[-\log p(Y)]$$

Coin Flip Example: $Y \sim \text{Bernoulli}(x)$



Maximum uncertainty when coin is fair.

Mutual Information

$$I(X; Y) = H(X) - H(X | Y)$$

- Measures entropy reduction after observing Y
- How much information does Y carry about X ?

Computing MI as hard as doing inference.

Information-Theoretic Decision Making

At time t given history $\mathcal{Y}_{t-1} = \{y_1, a_1, \dots, y_{t-1}, a_{t-1}\}$ choose *most informative* action $a = \{1, \dots, A\}$:

$$a_t^* = \operatorname{argmax}_a I_a(X; Y_t \mid \mathcal{Y}_{t-1})$$

Problem 1 MI calculation requires posterior expectation:

$$I_a(X; Y_t \mid \mathcal{Y}_{t-1}) = \mathbb{E} \left[\log \frac{p_a(Y_t \mid X, \mathcal{Y}_{t-1})}{p_a(Y_t \mid \mathcal{Y}_{t-1})} \right]$$

Estimate over posterior samples $\{(x^i, y_t^i)\}_{i=1}^N \sim p(x \mid \mathcal{Y}_{t-1})p(y_t \mid x, a)$

Information-Theoretic Decision Making

$$I_a(X; Y_t | \mathcal{Y}_{t-1}) = \mathbb{E} \left[\log \frac{p_a(Y_t | X, \mathcal{Y}_{t-1})}{p_a(Y_t | \mathcal{Y}_{t-1})} \right]$$

Problem 2 Requires pointwise evaluation of log-predictive dist'n:

$$\log p_a(y_t | \mathcal{Y}_{t-1}) = \log \int p(x | \mathcal{Y}_{t-1}) p(y_t | x, a) dx$$

Plug-in estimate over *more* samples $\{x^{ij}\}_{j=1}^M \sim p(x | y_t^i, \mathcal{Y}_{t-1}, a)$:

$$\hat{I}_a = \frac{1}{N} \sum_{i=1}^N \log \frac{p_a(y_t^i | x^i, a)}{\frac{1}{M} \sum_{j=1}^M p(y_t^i | x^{ij}, a)}$$

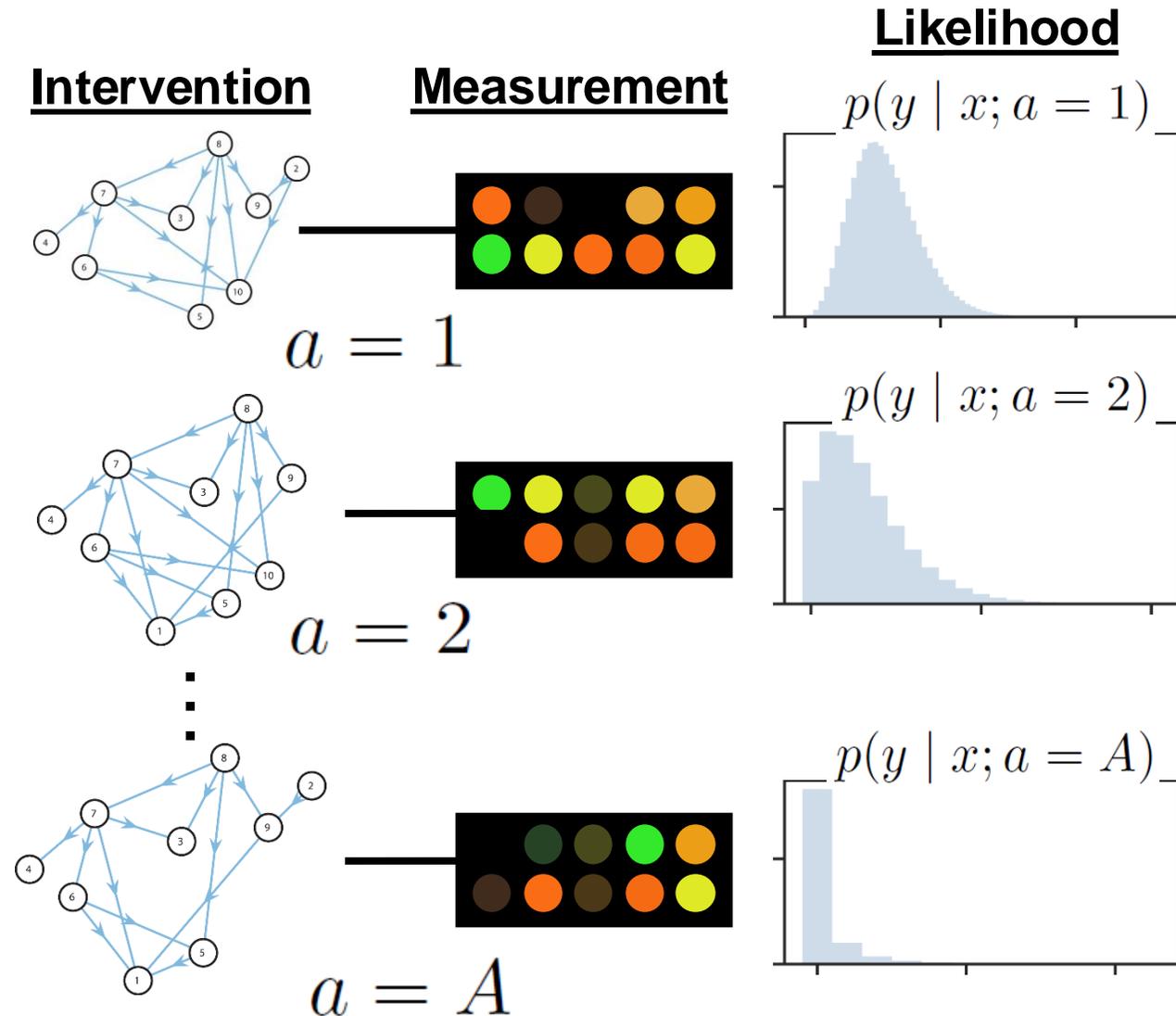
Empirical Information Planning

Given joint samples under each action compute Monte carlo **empirical mean** estimate:

$$\hat{I}_a = \frac{1}{N} \sum_{i=1}^N \log \frac{p_a(y^i | x^i, a)}{\frac{1}{M} \sum_{j=1}^M p(y^i | x^{ij}, a)}$$

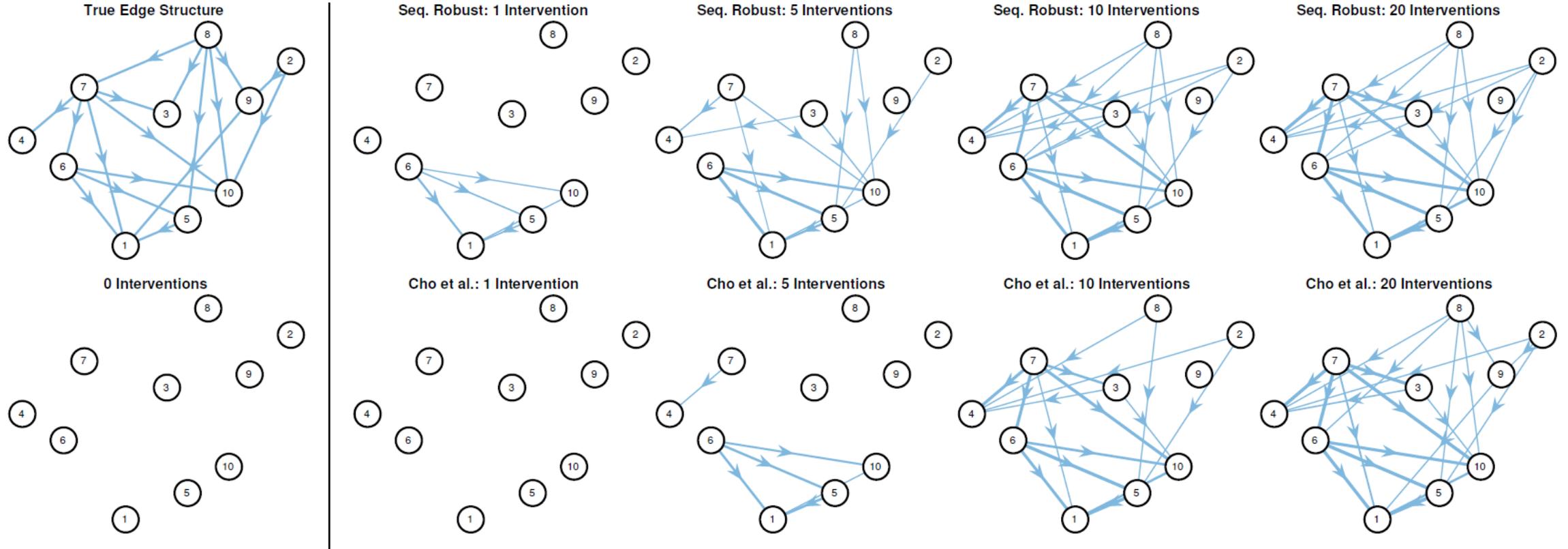
Planning based on estimated MI:

$$a^* = \arg \max_a \hat{I}_a(X; Y)$$



Problem: MI estimates are biased for finite samples

Gene Regulatory Network Inference

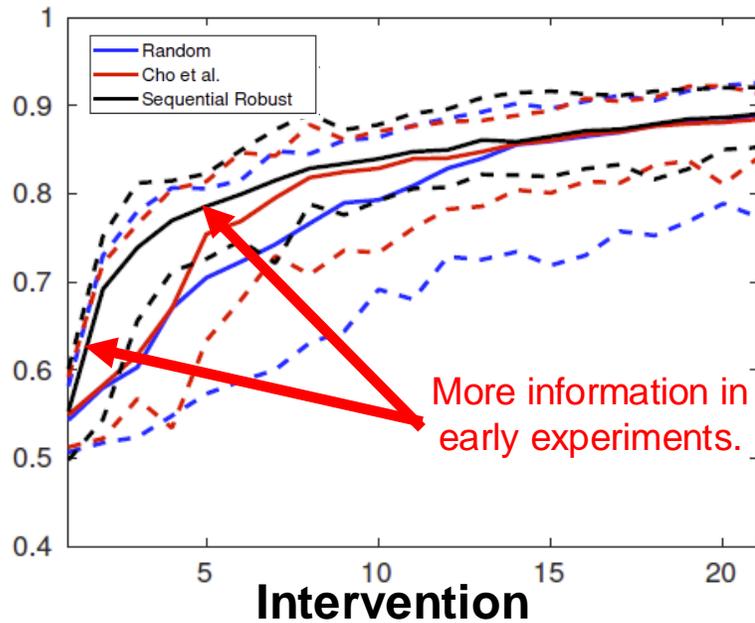


Edge width proportional to posterior probability

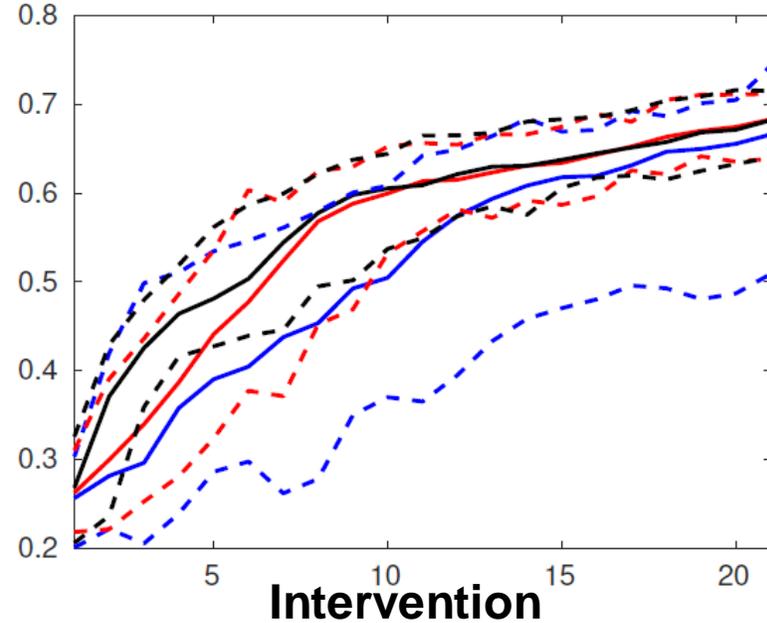
Gene Regulatory Network Inference

Directed Edge Prediction

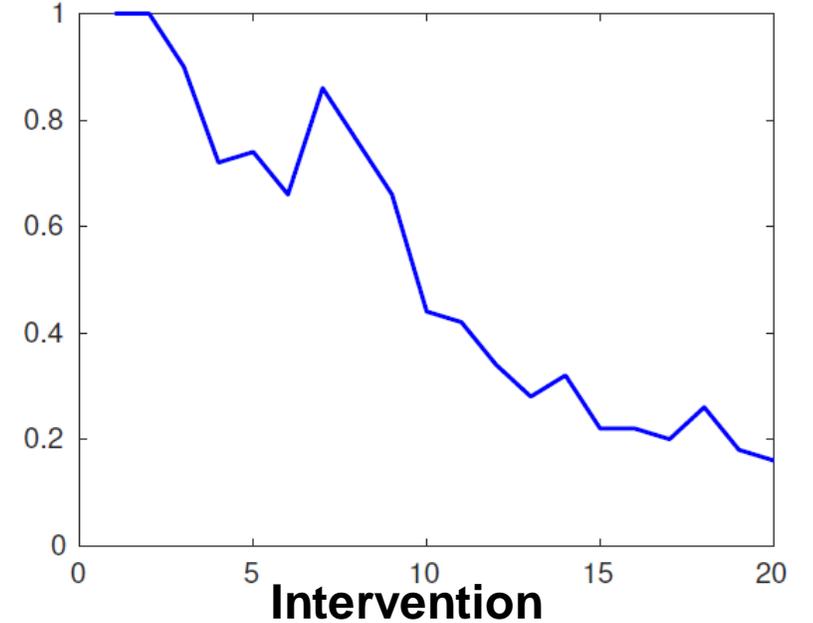
Area Under ROC



Area Under PRC



Resample Frequency



- Higher precision/recall w/ fewer interventions than non-robust method
- Resampling frequencies reduces as potential information gain is less

There's so much more to cover...

Models & Applications	AI Libraries	Representation Learning	Bayesian Nonparametrics	Advanced MCMC	Still more...
Course was mostly focused on algorithms, limited attention to modelling	Collection of tools for larger-scale AI	Unsupervised representation learning from structured data	A class of probability models where model complexity is inferred from the data	Avoiding random walk dynamics and allowing parallel computation	

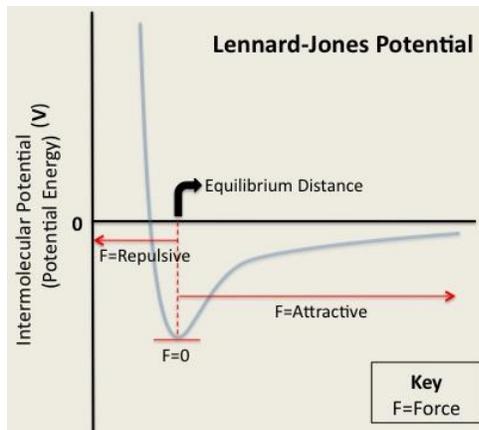
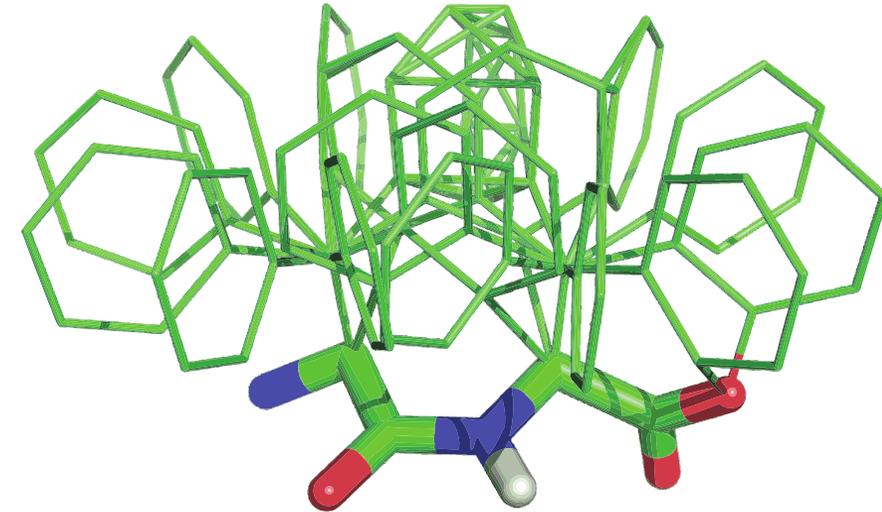
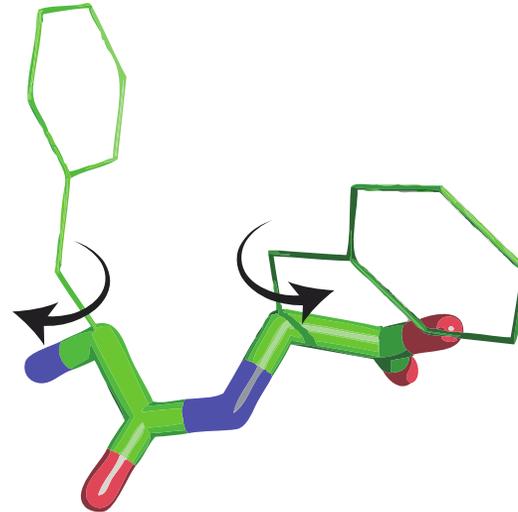
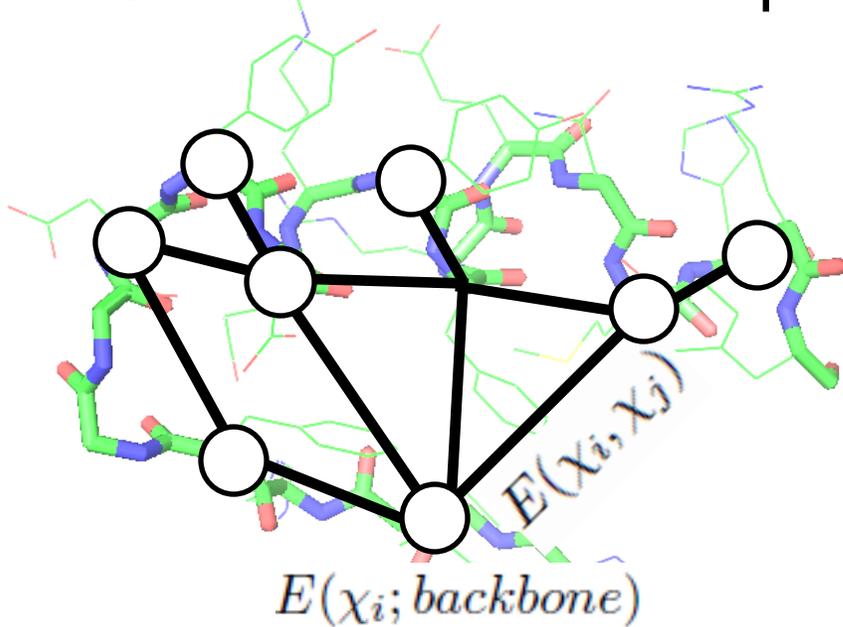
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Protein Side-Chain Structure Prediction

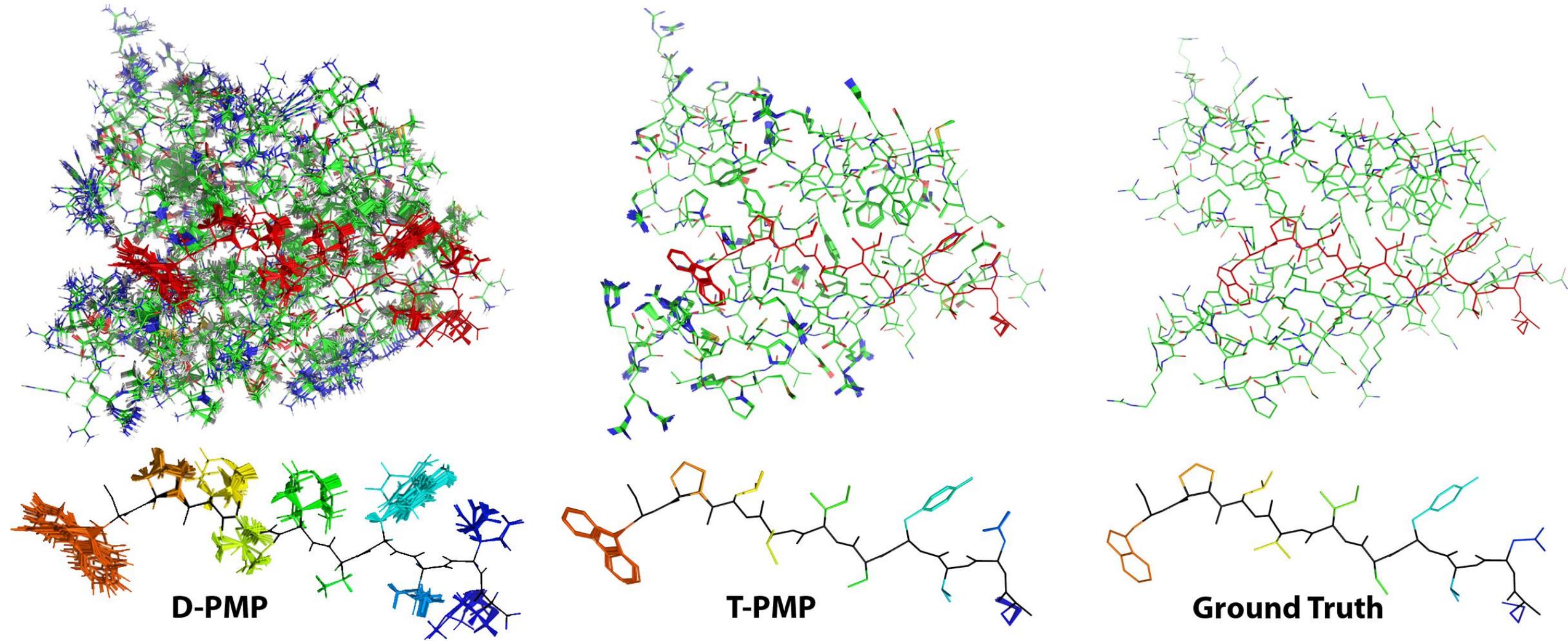
- A protein is a sequence of *amino acids*, each with a *side-chain*
- Side-chain structure prediction is MAP in pairwise MRF:

*Pacheco et al.,
ICML 2015*



- Pairwise potentials describe repulsive (Pauli exclusion) and attractive (van der Waals force) energetic interactions
- Predicting structure lets biochemists better understand and predict function

Protein Side-Chain Structure Prediction



- Qualitative example of side-chain predictions for one protein.
- Energy evaluated via state-of-the-art Rosetta package.

*Pacheco et al.,
ICML 2015*

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Libraries

Pyro.AI

- Python library for probabilistic programming
- Open-sourced by Uber AI Labs
- Implements many algorithms we have discussed (+more)
- Built on Pytorch / efficient inference via GPU



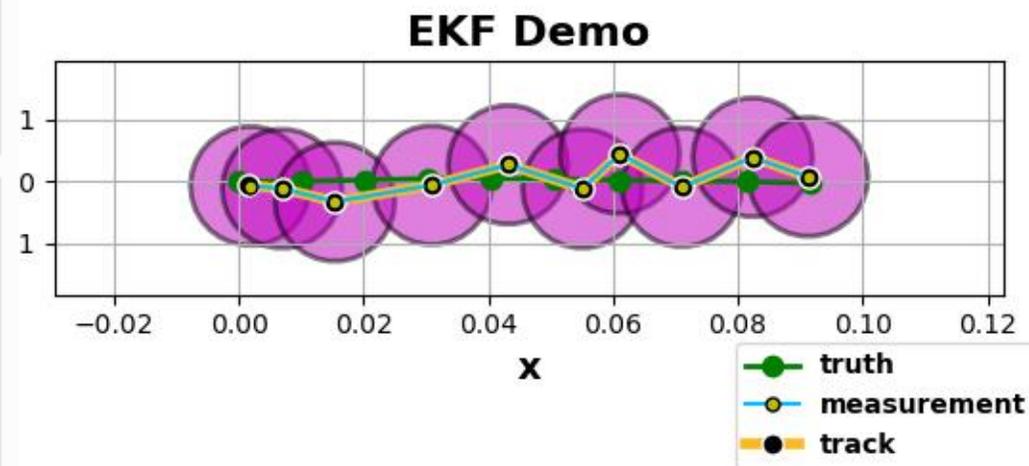
```
[ ]: def model(data):
    # a HalfNormal can be used here as well
    R = pyro.sample('pv_cov', dist.HalfCauchy(2e-6)) * torch.eye(4)
    Q = pyro.sample('measurement_cov', dist.HalfCauchy(1e-6)) * torch.eye(2)
    # observe the measurements
    pyro.sample('track_{}'.format(i), EKFDistribution(xs_truth[0], R, ncv,
                                                    Q, time_steps=num_frames),
               obs=data)
```

```
guide = AutoDelta(model) # MAP estimation
```

```
[ ]: optim = pyro.optim.Adam({'lr': 2e-2})
svi = SVI(model, guide, optim, loss=Trace_ELBO(retain_graph=True))
```

```
pyro.set_rng_seed(0)
pyro.clear_param_store()
```

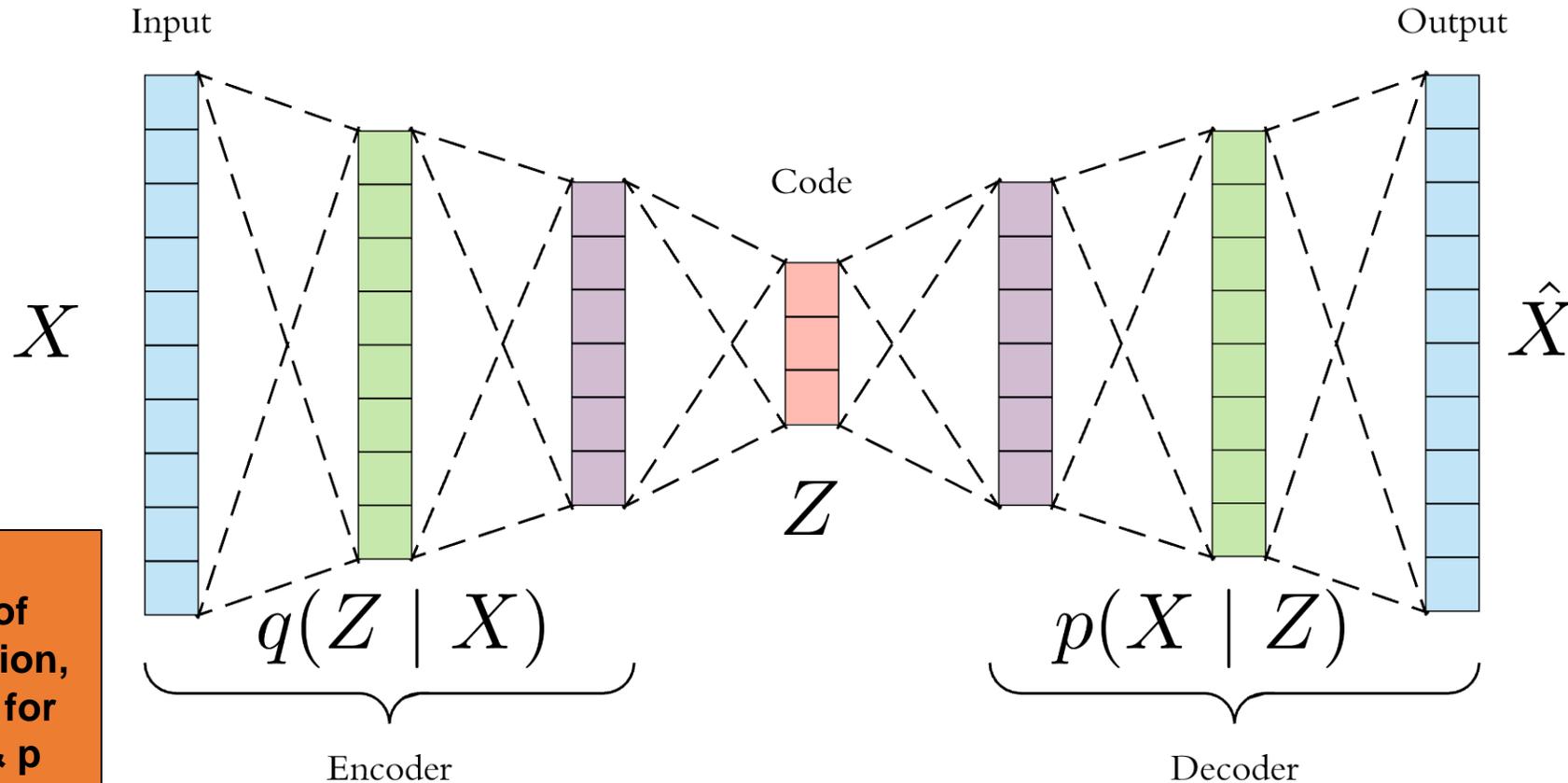
```
for i in range(250 if not smoke_test else 2):
    loss = svi.step(zs)
    if not i % 10:
        print('loss: ', loss)
```



There's so much more to cover...

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Variational Autoencoder



Train by minimizing reconstruction loss and fit to marginal:

$$\min \mathcal{L}(x, \hat{x}) + KL(q(z | x) || p(z))$$

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Gaussian Processes (GPs)

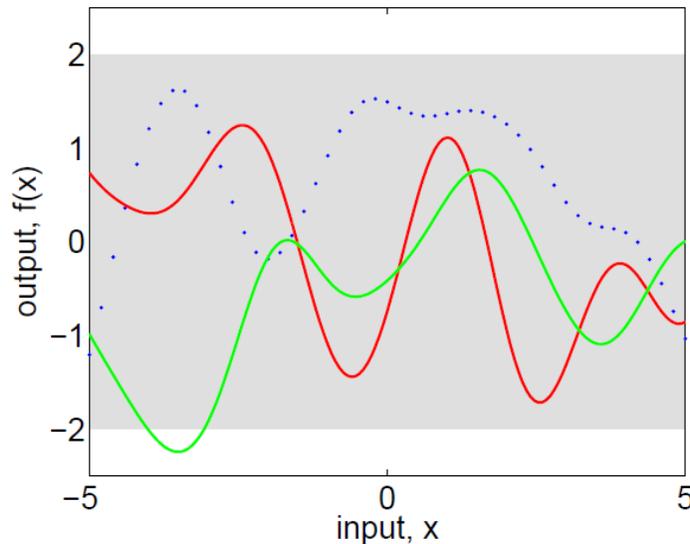
Distribution over random continuous functions...

$$\mathbf{f}_* \sim \mathcal{N}(\mathbf{0}, \underbrace{K(X_*, X_*)}_{\text{Kernel function}})$$

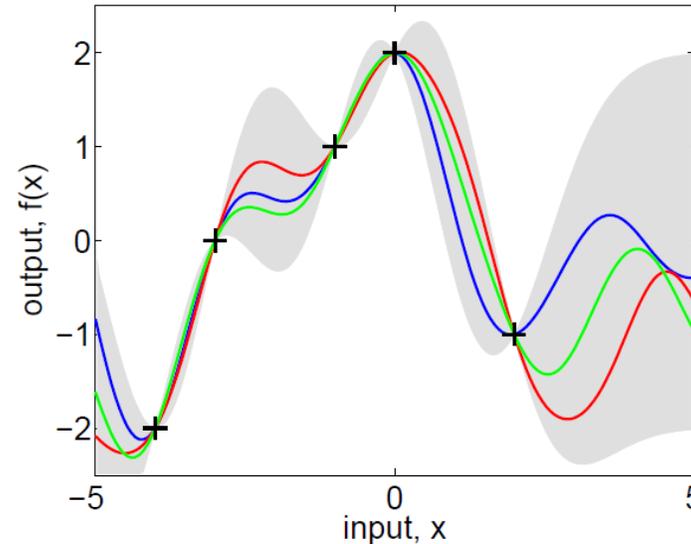
Kernel function encodes correlation between evaluation points in the domain

GPs are generative models...

- Can sample function from prior
- Tractable posterior
- Posterior predictive



(a), prior

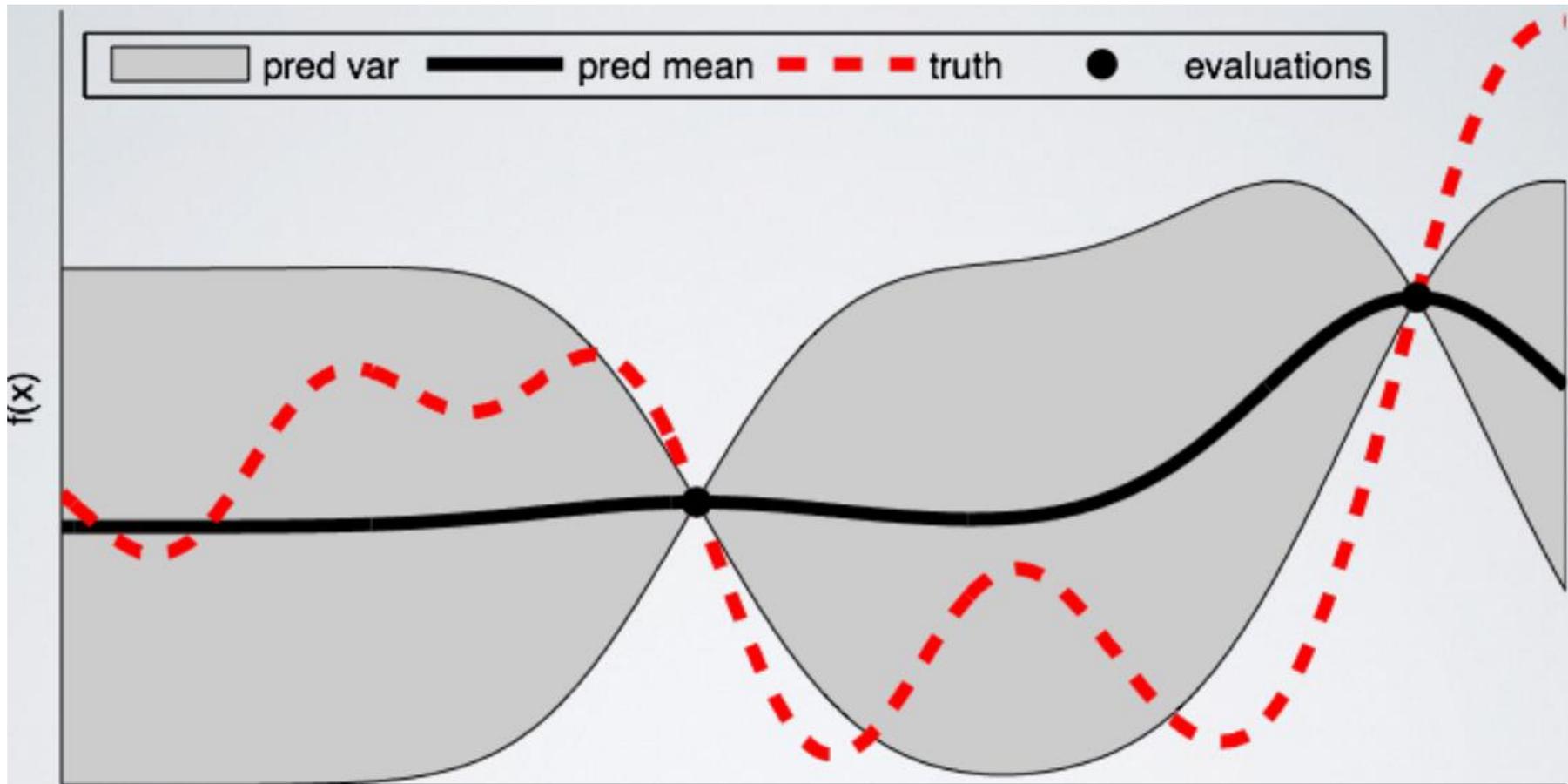


(b), posterior

...equivalent to Bayesian linear regression in function space

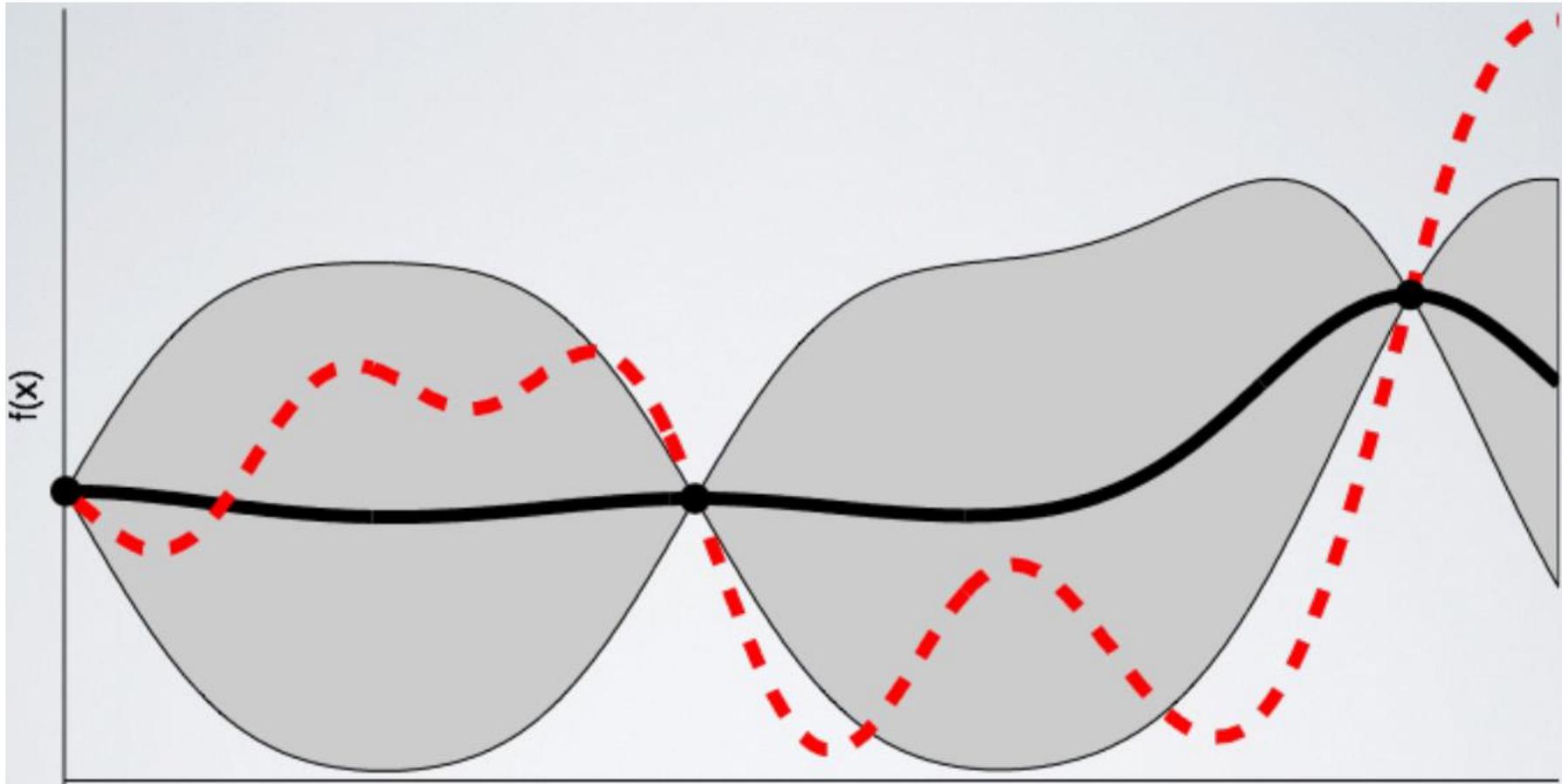
Bayesian Optimization

Global optimization of random functions: $\min_x f(x)$



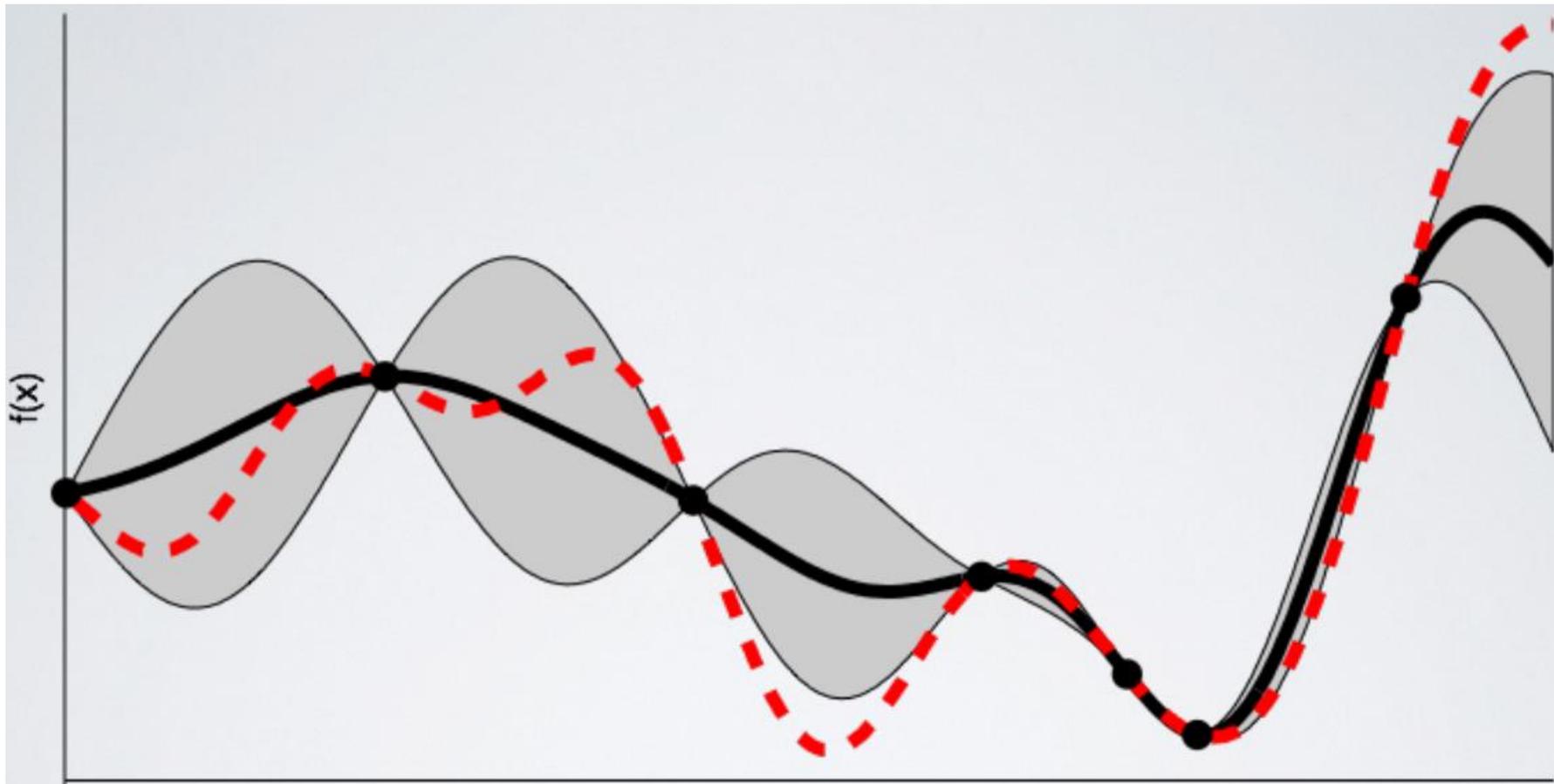
Bayesian Optimization

Iteratively updates distribution over function value (regression)



Bayesian Optimization

The function is well-approximated around the minimizer

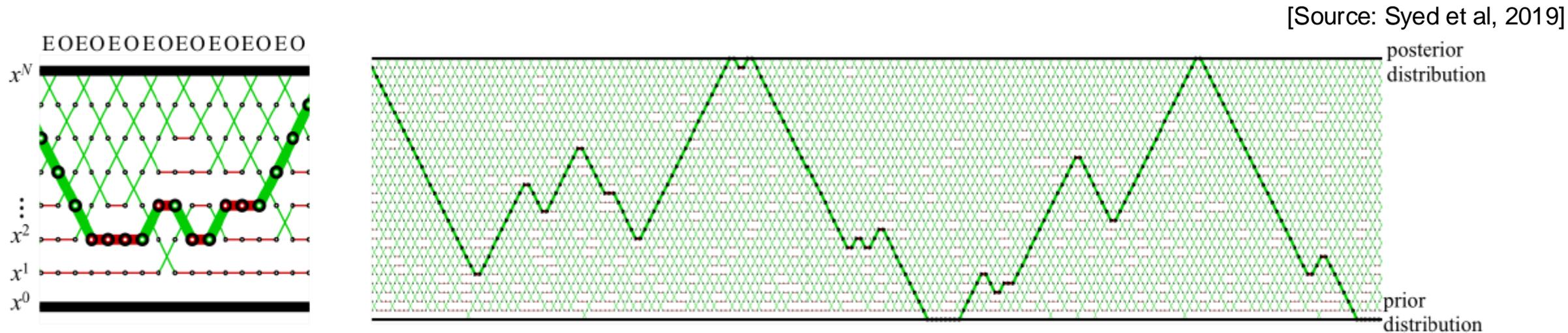


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Advanced Markov Chain Monte Carlo

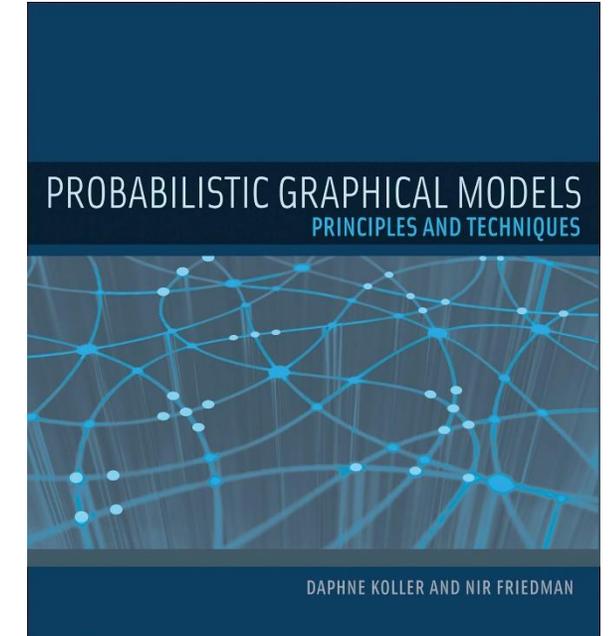
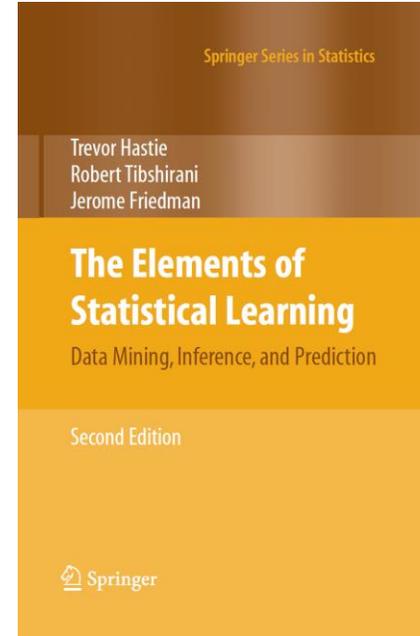
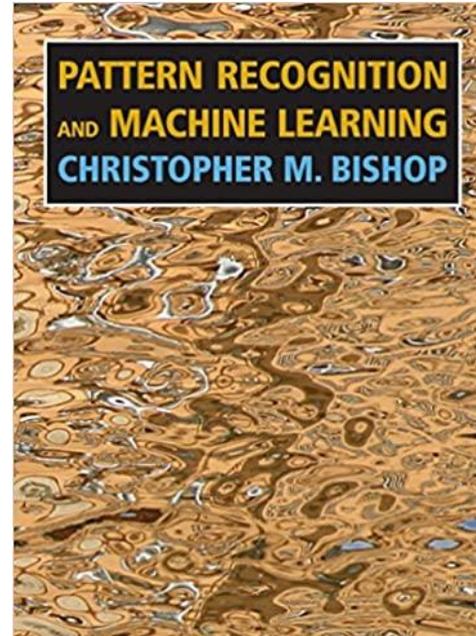
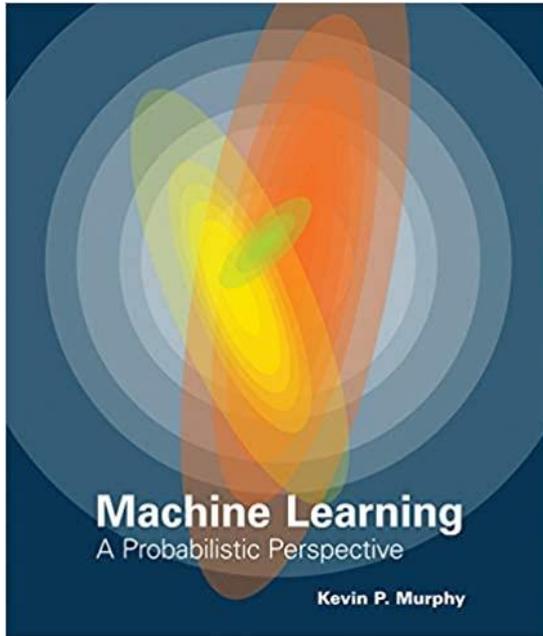
Advanced MCMC techniques reduce sample complexity and avoid getting stuck in local energy minima



Example: Parallel tempering exchange replicates across multiple MCMC chains running in (embarrassingly) parallel

Resources

We covered a lot of ground...but there is a lot more to cover!



Important conferences to follow...

- **NeurIPS**
- **ICML**
- **AISTATS**
- **ICLR**
- **ICRA**
- **IROS**
- **COLT**
- **IJCAI**
- **AAAI**
- **UAI**